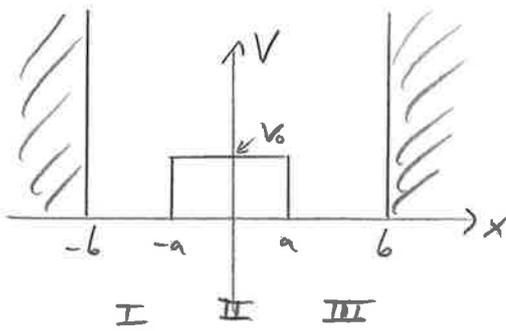


①



zeitunabh. SG, $k_I = \sqrt{\frac{2mE}{\hbar^2}}$, $k_{II} = \sqrt{\frac{2m(E-V_0)}{\hbar^2}}$

$$\psi_I'' = -k_I^2 \psi_I; \quad \psi_{II}'' = -k_{II}^2 \psi_{II}; \quad \psi_{III}'' = -k_I^2 \psi_{III}$$

Lsg. $\psi_I = c_1 e^{ik_I x} + c_2 e^{-ik_I x};$

$$\psi_{II} = c_3 (e^{ik_{II} x} + e^{-ik_{II} x})$$

$$\psi_{III} = c_1 e^{-ik_I x} + c_2 e^{ik_I x}$$

wegen $\psi(x) = \psi(-x)$ gerade

Randbed.: $0 \stackrel{!}{=} \psi_I(-b) = c_1 e^{-ik_I b} + c_2 e^{ik_I b} \quad (1)$

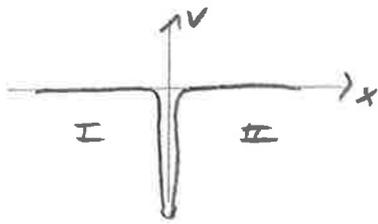
ψ stetig @ $-a$: $c_1 e^{-ik_I a} + c_2 e^{ik_I a} = c_3 (e^{-ik_{II} a} + e^{ik_{II} a}) \quad (2)$

ψ' stetig @ $-a$: $ik_I (c_1 e^{-ik_I a} - c_2 e^{ik_I a}) = ik_{II} c_3 (e^{-ik_{II} a} - e^{ik_{II} a}) \quad (3)$

teile (3) durch (2), benutze (1), $e^{ix} = \cos x + i \sin x, \dots$

$$\Rightarrow k_I \cot(k_I(b-a)) = k_{II} \tan(k_{II} a)$$

2a



zeitunabh. SG, $H\psi = E\psi$, $(\partial_x^2 + V_0\delta) \psi = -\frac{2mE}{\hbar^2} \psi$

$$\Rightarrow \int_{-E}^E dx (\psi'' + V_0\delta\psi) = -\frac{2mE}{\hbar^2} \int_{-E}^E dx \psi$$

$$\epsilon \rightarrow 0: \psi'(0^+) - \psi'(0^-) + V_0\psi(0) = 0 ;$$

ψ stetig bei $x=0$ (denn sonst $\psi' \ni \delta$, $\psi'' \ni \delta'$, aber $V \neq \delta'$)

$$\Rightarrow \psi(0^-) = \psi(0^+)$$

2b

Bindungszeit, $E < 0$, $\kappa = \sqrt{-\frac{2mE}{\hbar^2}} > 0$,

SG $(\partial_x^2 + V_0)\psi = \kappa^2\psi$

Lsg $\psi_I = c_1 e^{\kappa x}$ (wegen $\psi_I(-\infty) = 0$ (Gem $e^{-\kappa x}$))

$\psi_{II} = c_2 e^{-\kappa x}$ (wegen $\psi_{II}(\infty) = 0$ (Gem $e^{+\kappa x}$))

aus 2a: $\psi(0^-) = \psi(0^+) \Rightarrow c_1 = c_2 \equiv c$

$$\psi'(0^-) = c\kappa = \psi'(0^+) + V_0\psi(0) = c(-\kappa) + V_0c$$

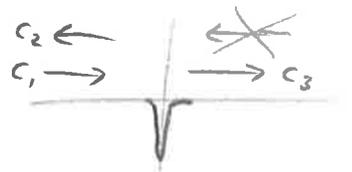
$$\Rightarrow \kappa = V_0/2, \quad E = -\frac{\hbar^2 V_0^2}{8m}$$

Norm $\frac{1}{2|c|^2} = \int_0^\infty dx e^{-2\kappa x} = \frac{1}{-2\kappa} e^{-2\kappa x} \Big|_0^\infty = 0 - \frac{1}{-2\kappa} = \frac{1}{2\kappa}$

$$\Rightarrow \psi(x) = \sqrt{\frac{V_0}{2}} e^{-V_0|x|/2}$$

2c

jetzt $E > 0$, $k = \sqrt{\frac{2mE}{\hbar^2}} > 0$,



SG $(\partial_x^2 + V_0\delta)\psi = -k^2\psi$

$\psi_I = c_1 e^{ikx} + c_2 e^{-ikx}$, $\psi_{II} = c_3 e^{ikx}$

aus 2a: $c_1 + c_2 = c_3$; $ik(c_1 - c_2) = ikc_3 + V_0c_3$

$$\Rightarrow 2c_1 = c_3(2 + \frac{V_0}{ik}), \quad |c_1|^2 = |c_3|^2(1 + \frac{V_0^2}{4k^2}), \quad T = \frac{1}{1 + V_0^2/4k^2}$$

$$R = 1 - T = \frac{1}{1 + 4k^2/V_0^2}$$

3a

$$\text{zeitabhängige } \psi, \quad i\hbar \partial_t \begin{pmatrix} \psi_1 \\ \psi_2 \end{pmatrix} = -\mu B \frac{\hbar}{2} \begin{pmatrix} \psi_1 \\ -\psi_2 \end{pmatrix}$$

$$\Rightarrow \psi(t) = \begin{pmatrix} \cos \frac{\alpha}{2} \cdot e^{i\mu B t/2} \\ \sin \frac{\alpha}{2} \cdot e^{-i\mu B t/2} \end{pmatrix}$$

3b

$$\begin{aligned} \langle S_x \rangle &= \frac{\hbar}{2} (\psi_1^*, \psi_2^*) \begin{pmatrix} \psi_2 \\ \psi_1 \end{pmatrix} = \frac{\hbar}{2} (\psi_1^* \psi_2 + \psi_2^* \psi_1) \\ &= \frac{\hbar}{2} \cos \frac{\alpha}{2} \sin \frac{\alpha}{2} (e^{-i\mu B t} + e^{i\mu B t}) = \hbar \cos \frac{\alpha}{2} \sin \frac{\alpha}{2} \cos(\mu B t) \end{aligned}$$

$$\langle S_y \rangle = -\frac{i\hbar}{2} (\psi_1^* \psi_2 - \psi_2^* \psi_1) = -\hbar \cos \frac{\alpha}{2} \sin \frac{\alpha}{2} \sin(\mu B t)$$

$$\langle S_z \rangle = \frac{\hbar}{2} (\psi_1^* \psi_1 - \psi_2^* \psi_2) = \frac{\hbar}{2} (\cos^2 \frac{\alpha}{2} - \sin^2 \frac{\alpha}{2}) \stackrel{!}{=} \frac{\hbar}{2} \cos \alpha$$

4

$$E_0 \leq E_\psi = \int dx N^* e^{-\alpha^2 x^2/2} \left(-\frac{\hbar^2}{2m} \partial_x^2 + \lambda x^4 \right) N e^{-\alpha^2 x^2/2}$$

$$\text{Norm } \frac{1}{|N|^2} = \int dx e^{-\alpha^2 x^2} = \frac{\sqrt{\pi}}{\alpha}$$

$$= \frac{\alpha}{\sqrt{\pi}} \int dx e^{-\alpha^2 x^2} \left(-\frac{\hbar^2}{2m} [-\alpha^2 + \alpha^4 x^2] + \lambda x^4 \right)$$

$$= \frac{\alpha}{\sqrt{\pi}} \left\{ \frac{\hbar^2 \alpha^2}{2m} \int dx e^{-\alpha^2 x^2} + \frac{\hbar^2 \alpha^4}{2m} \int dx (-x^2) e^{-\alpha^2 x^2} + \lambda \int dx (-x^2)^2 e^{-\alpha^2 x^2} \right\}$$

$\int dx (-x^2) e^{-\alpha^2 x^2} = \partial_{\alpha^2} \int dx e^{-\alpha^2 x^2} = -\frac{\sqrt{\pi}}{2\alpha^3}$
 $\int dx (-x^2)^2 e^{-\alpha^2 x^2} = \partial_{\alpha^2}^2 \int dx e^{-\alpha^2 x^2} = +\frac{3\sqrt{\pi}}{4\alpha^5}$

$$= \frac{\hbar^2 \alpha^2}{4m} + \frac{3\lambda}{4\alpha^4}$$

$$\text{Min? } 0 \stackrel{!}{=} \partial_{\alpha^2} E_\psi = \frac{\hbar^2}{4m} - \frac{3\lambda}{2\alpha^6} \Rightarrow \alpha^6 = \frac{6\lambda m}{\hbar^2}$$

$$\text{Min oder Max? } \partial_{\alpha^2}^2 E_\psi = 0 + \frac{9\lambda}{2\alpha^8} > 0 \quad \checkmark \text{ Min}$$

$$\Rightarrow E_{\psi, \text{min}} = \left(\frac{\hbar^4 \lambda}{4m^2} \right)^{1/3} \left(\frac{3\sqrt{3}}{4} \right)^{1/3} \approx 1.08169 \dots$$

Abweichung (2%)
nach oben.

5a

$$\langle S_x \rangle = \text{Sp}(\rho S_x) = \frac{1}{8} \text{Sp} \left(\begin{pmatrix} 3 & i \\ -i & 1 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \right) \\ = \frac{1}{8} \text{Sp} \begin{pmatrix} i & 3 \\ -1 & -i \end{pmatrix} = 0$$

$$\langle S_z \rangle = \text{Sp}(\rho S_z) = \frac{1}{8} \text{Sp} \left(\begin{pmatrix} 3 & i \\ -i & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \right) \\ = \frac{1}{8} \text{Sp} \begin{pmatrix} 3 & -i \\ -1 & -1 \end{pmatrix} = \frac{1}{4}$$

$$\text{Sp}(\rho^2) = \frac{1}{16} \text{Sp} \left(\begin{pmatrix} 3 & i \\ -i & 1 \end{pmatrix} \begin{pmatrix} 3 & i \\ -i & 1 \end{pmatrix} \right) = \frac{1}{16} \text{Sp} \begin{pmatrix} 10 & 2 \\ 2 & 2 \end{pmatrix} = \frac{3}{4} < 1$$

\Rightarrow gemischt

$$u^\dagger u = 11$$

5b

$$\text{Sp}(\rho_t^2) = \text{Sp}(U \rho_0 U^\dagger U \rho_0 U^\dagger) \stackrel{u^\dagger u = 11}{=} \text{Sp}(U \rho_0^2 U^\dagger) \\ \text{Sp zyklisch} \rightarrow \text{Sp}(U^\dagger U \rho_0^2) = \text{Sp}(\rho_0^2)$$

\Rightarrow wenn Zustand zum Zeitpunkt t_0 gemischt,
bleibt er gemischt für alle t .