

29 (a) I OK

II $\det(A - \lambda E) = \dots = (1-\lambda)(4-\lambda)(7-\lambda)$, $\lambda_{1,2,3} = \{1, 4, 7\}$

III $S_p(A) = 3+4+5 = 12 \Rightarrow \sum \lambda_i = 12 \quad \checkmark$

IV $(A - \lambda_1 E) \vec{f}_1 = \vec{0} = \begin{pmatrix} 2 & -2 & 0 \\ -2 & 3 & -2 \\ 0 & -2 & 4 \end{pmatrix} \vec{f}_1 \Rightarrow \vec{f}_1 = \frac{1}{3} \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix} \quad \bullet$

$$\begin{pmatrix} -1 & -2 & 0 \\ -2 & 0 & -2 \\ 0 & -2 & 1 \end{pmatrix} \vec{f}_2 = \vec{0} \Rightarrow \vec{f}_2 = \frac{1}{3} \begin{pmatrix} -2 \\ 1 \\ 2 \end{pmatrix} \quad \bullet, \quad \begin{pmatrix} -4 & -2 & 0 \\ -2 & -3 & -2 \\ 0 & -2 & 2 \end{pmatrix} \vec{f}_3 = \vec{0} \Rightarrow \vec{f}_3 = \frac{1}{3} \begin{pmatrix} 1 \\ -2 \\ 2 \end{pmatrix} \quad \bullet$$

V Ortho : OK (gilt nur Kopf)

VI Rechts? z.B. $\vec{f}_1 \times \vec{f}_2 = \frac{1}{9} (3, -6, 6) = \vec{f}_3 \quad \checkmark \quad \bullet$

VII $A' = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & 1 \end{pmatrix}, D = \frac{1}{3} \begin{pmatrix} 2 & 2 & 1 \\ -2 & 1 & 2 \\ 1 & -2 & 2 \end{pmatrix} \quad \bullet$

(b) $\ddot{\vec{r}}' = -\omega^2 A' \vec{r}' \quad , \quad \dot{\vec{r}}'(0) = D \vec{0} = \vec{0}, \quad \vec{r}'(0) = \frac{2}{3} R D \begin{pmatrix} 4 \\ -1 \\ 1 \end{pmatrix} = \frac{2R}{9} \begin{pmatrix} 9 \\ -1 \\ 0 \end{pmatrix} = 2R \begin{pmatrix} 1 \\ -1 \\ 0 \end{pmatrix} \quad \bullet$

$$\left. \begin{array}{l} \ddot{x}' = -\omega^2 x', \quad x'(0) = 0, \quad x'(0) = 2R \\ \ddot{y}' = -4\omega^2 y', \quad y'(0) = 0, \quad y'(0) = -2R \\ \ddot{z}' = -7\omega^2 z', \quad z'(0) = 0, \quad z'(0) = 0 \end{array} \right\} \quad \vec{r}'(t) = \begin{pmatrix} 2R \cos(\omega t) \\ -2R \cos(2\omega t) \\ 0 \end{pmatrix}$$

30 (a) $H = \begin{pmatrix} 5 & -4 & -2 \\ -4 & 5 & -2 \\ -2 & -2 & 8 \end{pmatrix}, \quad \vec{a} = 6 \begin{pmatrix} 2 \\ 2 \\ 1 \end{pmatrix} \quad \bullet$

I OK

II $\det(H - \lambda E) = \dots = -\lambda(9-\lambda)^2, \quad \lambda_{1,2,3} = \{0, 9, 9\}$

III $5+5+8 = 9+9 \quad \checkmark$

IV $H \vec{f}_1 = \vec{0} \Rightarrow \vec{f}_1 = \frac{1}{3} \begin{pmatrix} 2 \\ 2 \\ 1 \end{pmatrix}, \quad \vec{f}_{2,3} : \begin{pmatrix} -4 & -4 & -2 \\ -4 & -4 & -2 \\ -2 & -2 & 1 \end{pmatrix} \begin{pmatrix} r \\ s \\ t \end{pmatrix} = \vec{0} \Rightarrow (\text{z.B.}) \quad \vec{f}_2 = \frac{1}{3} \begin{pmatrix} -2 \\ 1 \\ 2 \end{pmatrix}$

V, VI: $\vec{f}_3 = \vec{f}_1 \times \vec{f}_2 = \frac{1}{3} \begin{pmatrix} 1 \\ -2 \\ 2 \end{pmatrix}$

VII $H' = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 9 & 0 \\ 0 & 0 & 9 \end{pmatrix}, \quad D = \frac{1}{3} \begin{pmatrix} 2 & 2 & 1 \\ -2 & 1 & 2 \\ 1 & -2 & 2 \end{pmatrix} \quad \bullet$

(b) $9y'^2 + 9z'^2 = \vec{a}' \cdot \vec{r}' \quad , \quad \vec{a}' = D \vec{a} = 6 D \begin{pmatrix} 2 \\ 2 \\ 1 \end{pmatrix} = 36 \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}$
 $= 36x' \quad \bullet$

$x' = \frac{3}{6}(y'^2 + z'^2) \quad \text{ist Rotationsellipsoid} \quad \bullet,$

\vec{e} ist \vec{f}_1 , also $\vec{e} = \frac{1}{3} \begin{pmatrix} 2 \\ 2 \\ 1 \end{pmatrix} \quad \bullet$

(c) $\vec{e}' \cdot \vec{r}' = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \cdot \vec{r}' = x' = c, \quad q_m = \frac{1}{100m} (y'^2 + z'^2) \Rightarrow 20m \quad \bullet$

28, 31 verneide ich nicht.. selber..