

Elements of fluid dynamics for the modeling of heavy-ion collisions

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Elements of fluid dynamics for the modeling of heavy-ion collisions

Three lectures:

- Overview on the dynamics of relativistic perfect fluids
- Application of perfect relativistic fluid dynamics to the description of high-energy nucleus–nucleus collisions
- Beyond perfect relativistic fluid dynamics



Elements of fluid dynamics for the modeling of heavy-ion collisions

Three lectures:

- Overview on the dynamics of relativistic perfect fluids

phenomenological approach

- reminder(?) on non-relativistic fluid dynamics (“hydrodynamics”)
- fundamental equations of perfect relativistic fluid dynamics
- an example of solution
- Application of perfect relativistic fluid dynamics to the description of high-energy nucleus–nucleus collisions
- Beyond perfect relativistic fluid dynamics

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phenomenology & experiment

- fluid dynamical modeling of the fireball created in the collisions
 - yields a surprisingly good rendering of some measurements
 - ... at the cost of introducing elements that are not within perfect hydrodynamics
- Beyond perfect relativistic fluid dynamics

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theoretical approaches

- many ideas: dissipative fluid dynamics / including hydrodynamical fluctuations / or “non-hydro modes”... ➔ out-of-equilibrium physics
- ... coming from the underlying “microscopic” physics (transport) or invoking strong-coupling scenarios

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Lecture I:

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- reminder(?) on non-relativistic fluid dynamics (“hydrodynamics”)
- fundamental equations of perfect relativistic fluid dynamics
- an example of solution (possibly in lecture II)
- Application of perfect relativistic fluid dynamics to the description of high-energy nucleus-nucleus collisions
- Beyond perfect relativistic fluid dynamics

Elements of fluid dynamics...

General references:

- A few textbooks aimed at physicists:

- Landau & Lifshitz, vol.6: "Fluid Mechanics"

(L&L-style..., a short chapter on relativistic hydro)

- Guyon, Hulin, Petit, Mitescu: "Physical Hydrodynamics"

(more phenomenological, only non-relativistic fluid dynamics)

- Rezzola & Zanotti, "Relativistic Hydrodynamics"

(by astrophysicists with an interest in numerical fluid dynamics)

- General Relativity / Cosmology textbooks often contain a chapter on relativistic fluid dynamics

Weinberg, "Gravitation and Cosmology"

Misner, Thorne, Wheeler, "Gravitation"

Elements of fluid dynamics...

- Review articles

- Andersson & Comer, “Relativistic fluid dynamics: Physics for many scales”
[arXiv:gr-qc/0605010](https://arxiv.org/abs/gr-qc/0605010)

- Romatschke, “New developments in relativistic viscous hydrodynamics”
[arXiv:0902.3663](https://arxiv.org/abs/0902.3663)

- Ollitrault, “Relativistic hydrodynamics for heavy ion collisions”
[arXiv:0708.2443](https://arxiv.org/abs/0708.2443)

- ... and many others

- Online lecture notes

- a few chapters in Blandford & Thorne, “Applications of Classical Physics” (will soon become a book; use your favorite search engine...)

- N.B. @ <http://www.physik.uni-bielefeld.de/~borghini/Teaching/Hydrodynamics>

(sorry for the lack of modesty)

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Lecture I:

- Overview on the dynamics of relativistic perfect fluids

phenomenological approach

- reminder(?) on non-relativistic fluid dynamics (“hydrodynamics”)
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Non-relativistic fluid dynamics

Classical definition:

A “fluid” is a continuous medium that keeps on deforming as long as it is subject to tangential forces (“shear stresses” \neq normal stresses):

gas, liquid, plasma...

➡ \neq deformable solid (elastic / plastic), which will reach an equilibrium

Non-relativistic fluid dynamics

Classical definition:

A “fluid” is a **continuous medium** that keeps on deforming as long as it is subject to tangential forces (“shear stresses” \neq normal stresses):

gas, liquid, plasma...

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Continuous medium?

- for the mathematician, this makes life easier

 - ☛ “differentiable medium” is even better

- for the physicist, this is a **model**, thus open to discussion if need be

 - ☛ atoms exist, don't they?

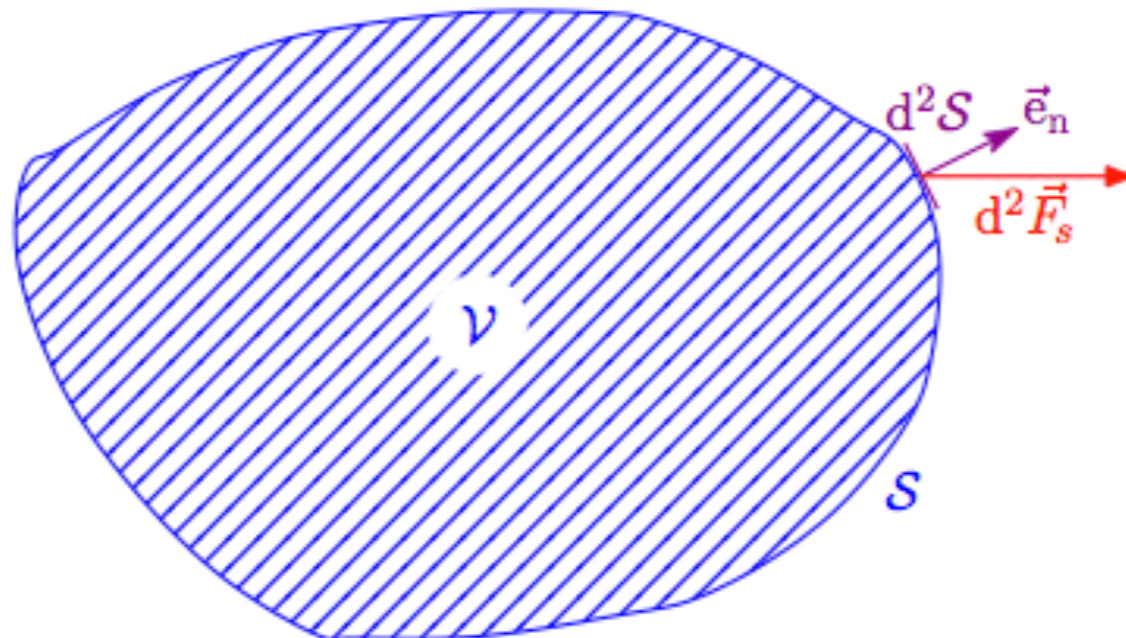
Well, so do fields, so who knows...

Non-relativistic fluid dynamics

Classical definition:

A “fluid” is a continuous medium that keeps on deforming as long as it is subject to tangential forces (“shear stresses” \neq normal stresses):

Idea: decompose the contact force – exerted by the neighboring fluid element(s) or by a wall / obstacle – per unit surface into a normal and a tangential part:



Non-relativistic fluid dynamics

Classical definition:

A “fluid” is a continuous medium that keeps on deforming as long as it is subject to tangential forces (“shear stresses” \neq normal stresses):

👉 In a fluid **at rest**, the contact forces are normal!
(hydrostatic) **pressure** forces

One introduces a **pressure field** $\mathcal{P}(t, \vec{r})$ at each point of the fluid

👉 will quickly be continuous, differentiable... at least by parts



Non-relativistic fluid dynamics

The “degrees of freedom” = dynamical variables

A “fluid” is a continuous medium characterized by its

- mass density $\rho(t, \vec{r})$
- pressure $\mathcal{P}(t, \vec{r})$
- local flow velocity $\vec{v}(t, \vec{r})$
- energy density $e(t, \vec{r})$
- ... further dynamical fields?

at each time and position.

☞ all of them are assumed to behave smoothly, at least by parts

☞ These “mesoscopic” quantities deserve a better definition, in terms of more microscopic ones... Will come later!

Non-relativistic fluid dynamics

The “degrees of freedom” = dynamical variables

A “fluid” is a continuous medium characterized by its

- mass
- pressure
- local
- energy
- ...

at each

parts

Throughout these lectures, I consider a single, simple fluid:

- single “component”: one **mass density** / **particle number** and one **velocity field** only



no mixture!

- simple: electrically neutral, non-magnetic...

👉 These “mesoscopic” quantities deserve a better definition, in terms of more microscopic ones... Will come later!

Non-relativistic fluid dynamics

The “degrees of freedom” = dynamical variables

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- ... further dynamical fields?

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☞ all of them are assumed to **behave smoothly**, at least by parts

?

☞ These **“mesoscopic”** quantities deserve a better definition, in terms of more microscopic ones... Will come later!

Model of a continuous medium

... the hidden physical assumptions

System (of particles / fields) can be divided in thought in cells that fulfill two contradictory conditions:

- they must be large enough that quantities defined as averages over their content (e.g.: mass density, average particle velocity...) have small fluctuations

👉 cell size \gg mean free path ℓ_{mfp}

- they must be small enough to remain statistically homogeneous, i.e. the system “mesoscopic” properties do not vary too much over the cell

👉 cell size \ll scale L of macroscopic gradients

Model of a continuous medium

an important dimensionless number

Two length scales:

- mean free path* ℓ_{mfp}
 - size L over which macroscopic fields vary ($\sim 1/|\partial_{\vec{r}}|$)
- 👉 The description as a continuous medium is meaningful iff

$$\text{Knudsen number } \text{Kn} \equiv \frac{\ell_{\text{mfp}}}{L} \ll 1$$

necessary consistency check (easily written... non-trivial!)

*strictly speaking, is well defined only for “dilute” systems

Non-relativistic fluid dynamics

The “degrees of freedom” = dynamical variables

A “fluid” is a continuous medium characterized by its

- mass density $\rho(t, \vec{r})$
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- energy density $e(t, \vec{r})$
- ... further dynamical fields?

at each time and position.

👉 We now need equations for these various fields!

Complicated-looking(?) equations, yet with a clear physical meaning!

Non-relativistic fluid dynamics

The dynamical equations of motion

Invoke the most basic laws of physics: **conservation equations!**

- **mass / particle number conservation**
- **momentum conservation** (or more generally, Newton's 2nd law)
- **energy conservation**

each of which are expressed locally.



Non-relativistic fluid dynamics

The dynamical equations of motion

Invoke the most basic laws of physics: **conservation equations!**

- **mass / particle number conservation** (equivalent since $\rho = nm$)
- momentum conservation (or more generally, Newton's 2nd law)
- energy conservation

each of which are expressed locally.

“Continuity equation”:

$$\frac{\partial \rho(t, \vec{r})}{\partial t} + \vec{\nabla} \cdot [\rho(t, \vec{r}) \vec{v}(t, \vec{r})] = 0$$

$$\frac{\partial n(t, \vec{r})}{\partial t} + \vec{\nabla} \cdot [n(t, \vec{r}) \vec{v}(t, \vec{r})] = 0$$

(Remember charge conservation in electrodynamics!)

Non-relativistic fluid dynamics

The dynamical equations of motion

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“**Continuity equation**”:

$$\partial_t \rho(t, \vec{r}) + \partial_i [\rho(t, \vec{r}) v^i(t, \vec{r})] = 0$$

$$\partial_t n(t, \vec{r}) + \partial_i [n(t, \vec{r}) v^i(t, \vec{r})] = 0$$

with a sum over repeated indices (here $i=1,2,3$)

Rem.: in non-Cartesian coordinates, replace partial by covariant derivatives

Non-relativistic fluid dynamics

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each of which are expressed locally.

Euler equation:

$$\rho(t, \vec{r}) \underbrace{\left[\partial_t \vec{v}(t, \vec{r}) + [\vec{v}(t, \vec{r}) \cdot \vec{\nabla}] \vec{v}(t, \vec{r}) \right]}_{\text{local fluid acceleration}} = \underbrace{-\vec{\nabla} \mathcal{P}(t, \vec{r})}_{\text{pressure forces}} + \underbrace{\vec{f}_v(t, \vec{r})}_{\text{volume forces (gravity...)}}$$



Non-relativistic fluid dynamics

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component-wise:

$$\rho(t, \vec{r}) \left[\partial_t v^i(t, \vec{r}) + v^j(t, \vec{r}) \partial_j v^i(t, \vec{r}) \right] = -\partial^i \mathcal{P}(t, \vec{r}) + (f_v)^i(t, \vec{r})$$



Non-relativistic fluid dynamics

The dynamical equations of motion

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or **Navier-Stokes equation:**

$$\rho(t, \vec{r}) \left[\partial_t \vec{v}(t, \vec{r}) + [\vec{v}(t, \vec{r}) \cdot \vec{\nabla}] \vec{v}(t, \vec{r}) \right] = -\vec{\nabla} \mathcal{P}(t, \vec{r}) + \vec{f}_{\text{visc.}}(t, \vec{r}) + \vec{f}_v(t, \vec{r})$$

with

$$\vec{f}_{\text{visc.}}(t, \vec{r}) \equiv \eta \vec{\nabla}^2 \vec{v}(t, \vec{r}) + \left(\zeta + \frac{\eta}{3} \right) \vec{\nabla} [\vec{\nabla} \cdot \vec{v}(t, \vec{r})]$$

Non-relativistic fluid dynamics

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WHAT THE...?

Non-relativistic fluid dynamics

The dynamical equations of motion

- **Momentum conservation** (or more generally, Newton's 2nd law) is expressed locally by...

- the **Euler equation**

$$\rho(t, \vec{r}) \left[\partial_t \vec{v}(t, \vec{r}) + [\vec{v}(t, \vec{r}) \cdot \vec{\nabla}] \vec{v}(t, \vec{r}) \right] = -\vec{\nabla} \mathcal{P}(t, \vec{r}) + \vec{f}_v(t, \vec{r})$$

☞ if the fluid is “perfect” (or “ideal”)

- the **Navier–Stokes equation**

$$\rho(t, \vec{r}) \left[\partial_t \vec{v}(t, \vec{r}) + [\vec{v}(t, \vec{r}) \cdot \vec{\nabla}] \vec{v}(t, \vec{r}) \right] = -\vec{\nabla} \mathcal{P}(t, \vec{r}) + \vec{f}_{\text{visc.}}(t, \vec{r}) + \vec{f}_v(t, \vec{r})$$

☞ if the fluid is “Newtonian”

- the **Burnett / super-Burnett equation**... .. if the fluid is...

↙ not kidding!

(Simple) fluid models

may be seen as properties of specific flows (more later)

- Perfect / ideal fluids:

... are such that there are **no dissipative effects** in them:

➡ neither shear stresses (friction) nor heat conduction

➡ “dry water”

(Feynman, Lectures on Physics vol.II, chap.40)

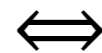
(Simple) fluid models

may be seen as properties of specific flows (more later)

- Perfect / ideal fluids:

... are such that there are **no dissipative effects** in them:

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At each point in the fluid, the **properties** as seen by an observer at rest w.r.t. the fluid—i.e. comoving with it—are **(locally) isotropic**.

In particular, the **momentum flux-density tensor** $T^{ij}(t, \vec{r})$ is **isotropic**:

➡ amount of i -th component of momentum transported in direction j

Conversely, “anisotropic fluids” are not perfect.

(So what?)

(Simple) fluid models

may be seen as properties of specific flows (more later)

- Perfect / ideal fluids:

... have a locally isotropic momentum flux-density tensor:

(amount of i -th component of momentum transported in direction j)

$$T^{ij}(t, \vec{r}) = \underbrace{\mathcal{P}(t, \vec{r}) \delta^{ij}}_{\text{thermal transport}} + \underbrace{\rho(t, \vec{r}) v^i(t, \vec{r}) v^j(t, \vec{r})}_{\text{convective transport}}$$

☞ only normal surface forces (no tangential stresses): pressure

Rems.:

- $T^{ij}(t, \vec{r})$ is symmetric.

- In non-Cartesian coordinates, replace δ^{ij} by the inverse metric tensor $g^{ij}(t, \vec{r})$.

(Simple) fluid models

may be seen as properties of specific flows (more later)

- **Dissipative** fluids:

... have a possibly **anisotropic momentum flux-density tensor**:

➡ because they admit **dissipative** currents

$$T^{ij}(t, \vec{r}) = \underbrace{\mathcal{P}(t, \vec{r}) \delta^{ij}}_{\text{thermal transport}} + \underbrace{\rho(t, \vec{r}) v^i(t, \vec{r}) v^j(t, \vec{r})}_{\text{convective transport}} + \underbrace{\pi^{ij}(t, \vec{r})}_{\text{diffusive transport}}$$

What is the form of the **viscous stress tensor** π^{ij} ?

➡ models (many!)

(Simple) fluid models

may be seen as properties of specific flows (more later)

- **Newtonian fluids:**

... have an **anisotropic momentum flux-density tensor** T^{ij} including a viscous stress tensor π^{ij} depending linearly on the **1st-order spatial derivatives** of the flow velocity:

$$T^{ij}(t, \vec{r}) = \mathcal{P}(t, \vec{r}) \delta^{ij} + \rho(t, \vec{r}) \mathbf{v}^i(t, \vec{r}) \mathbf{v}^j(t, \vec{r}) + \pi^{ij}(t, \vec{r})$$

with $\pi^{ij}(t, \vec{r}) \equiv -\eta(t, \vec{r}) \left[\partial^j v^i(t, \vec{r}) + \partial^i v^j(t, \vec{r}) - \frac{2}{3} \delta^{ij} \vec{\nabla} \cdot \vec{v}(t, \vec{r}) \right]$

$$- \zeta(t, \vec{r}) \delta^{ij} \vec{\nabla} \cdot \vec{v}(t, \vec{r})$$

$$\propto \delta^{ij} !$$

symmetric, traceless

where **shear viscosity η & bulk viscosity ζ** are independent of \vec{v} .

transport coefficients



(Simple) fluid models

may be seen as properties of specific flows (more later)

- **Newtonian** fluids:

... have a **shear viscosity** η and a **bulk viscosity** ζ .

☞ modify the surface forces:

- Normal force: with an “effective pressure”

$$\mathcal{P}(t, \vec{r}) = [\zeta(t, \vec{r}) - \frac{2}{3}\eta(t, \vec{r})] \underbrace{\vec{\nabla} \cdot \vec{v}(t, \vec{r})}_{\text{local expansion rate of the fluid}}$$

local expansion rate
of the fluid

- Tangential force: friction

“wet water” (Feynman, Lectures on Physics vol.II, chap.41)

... on a surface in the xy -plane, with the velocity along x , and a velocity gradient along the z direction:

$$F_x \propto \eta \partial_z v_x$$

(Simple) fluid models

may be seen as properties of specific flows (more later)

- **Newtonian** fluids:

... have an **anisotropic momentum flux-density tensor** T^{ij} including a viscous stress tensor π^{ij} depending linearly on the **1st-order spatial derivatives** of the flow velocity \vec{v} :

☞ define “**first-order dissipative hydrodynamics**”

- **Dissipative** fluids:

... with a **momentum flux-density tensor** with a viscous stress tensor depending linearly on the **2nd-order spatial derivatives** of \vec{v}

☞ define “**second-order dissipative hydrodynamics**”

- and so on... You can also devise other models (see e.g. Lecture III)

(Simple) fluid models

Ideal, first-, second-, third-order hydro...

- increasing complication (= precision of the description?)
- including higher and higher **gradients**

When are “low order” description appropriate?

☞ the **gradients** must be small!

⇔

size L over which macroscopic fields vary ($\sim 1/|\partial_{\vec{r}}|$) is large
...as was already argued above!

(+ looks like an expansion: is there any convergence?)

- and so on... You can also devise other models (see e.g. Lecture III)

Non-relativistic fluid dynamics

The dynamical equations of motion

- **Momentum conservation** (or more generally, Newton's 2nd law) is expressed locally by...

- the **Euler equation**

☞ perfect / ideal hydro

$$\rho(t, \vec{r}) \left[\partial_t \vec{v}(t, \vec{r}) + [\vec{v}(t, \vec{r}) \cdot \vec{\nabla}] \vec{v}(t, \vec{r}) \right] = -\vec{\nabla} \mathcal{P}(t, \vec{r}) + \vec{f}_v(t, \vec{r})$$

for **perfect / ideal** fluids

- the **Navier–Stokes equation**

☞ 1st order dissipative hydro

$$\rho(t, \vec{r}) \left[\partial_t \vec{v}(t, \vec{r}) + [\vec{v}(t, \vec{r}) \cdot \vec{\nabla}] \vec{v}(t, \vec{r}) \right] = -\vec{\nabla} \mathcal{P}(t, \vec{r}) + \vec{f}_{\text{visc.}}(t, \vec{r}) + \vec{f}_v(t, \vec{r})$$

for **Newtonian** fluids

- the **Burnett / super-Burnett equation...** ☞ 2nd / 3rd order hydro

Non-relativistic fluid dynamics

The dynamical equations of motion

- **Momentum conservation** (or more generally, Newton's 2nd law):

- the **Euler equation** (perfect / ideal hydro)

$$\rho(t, \vec{r}) \left[\partial_t \vec{v}(t, \vec{r}) + [\vec{v}(t, \vec{r}) \cdot \vec{\nabla}] \vec{v}(t, \vec{r}) \right] = -\vec{\nabla} \mathcal{P}(t, \vec{r}) + \vec{f}_v(t, \vec{r})$$

- the **Navier-Stokes equation** (1st order dissipative hydro)

$$\rho(t, \vec{r}) \left[\partial_t \vec{v}(t, \vec{r}) + [\vec{v}(t, \vec{r}) \cdot \vec{\nabla}] \vec{v}(t, \vec{r}) \right] = -\vec{\nabla} \mathcal{P}(t, \vec{r}) + \vec{f}_{\text{visc.}}(t, \vec{r}) + \vec{f}_v(t, \vec{r})$$

$$\vec{f}_{\text{visc.}}(t, \vec{r}) \equiv \eta \vec{\nabla}^2 \vec{v}(t, \vec{r}) + \left(\zeta + \frac{\eta}{3} \right) \vec{\nabla} [\vec{\nabla} \cdot \vec{v}(t, \vec{r})]$$

- the **Burnett / super-Burnett equations...** (2nd / 3rd order hydro)

are reformulations of

$$\underbrace{\partial_t [\rho(t, \vec{r}) v^i(t, \vec{r})]}_{\text{momentum density}} + \underbrace{\partial_j T^{ij}(t, \vec{r})}_{\text{momentum flux density}} = (f_v)^i(t, \vec{r})$$

momentum density momentum flux density

with **constant transport coefficients** in the dissipative case

Model of a continuous medium

a second important dimensionless number

Write down the Navier–Stokes equation in the simpler case $\vec{\nabla} \cdot \vec{v} = 0$ & in the absence of volume forces:

$$\rho(t, \vec{r}) \left[\partial_t \vec{v}(t, \vec{r}) + [\vec{v}(t, \vec{r}) \cdot \vec{\nabla}] \vec{v}(t, \vec{r}) \right] = -\vec{\nabla} \mathcal{P}(t, \vec{r}) + \eta \vec{\nabla}^2 \vec{v}(t, \vec{r})$$

“incompressible Navier–Stokes equation”

Solve it... become rich!

(Millenium Clay problem...)



Model of a continuous medium

a second important dimensionless number

Write down the Navier–Stokes equation in the simpler case $\vec{\nabla} \cdot \vec{v} = 0$ & in the absence of volume forces:

$$\rho(t, \vec{r}) \left[\partial_t \vec{v}(t, \vec{r}) + [\vec{v}(t, \vec{r}) \cdot \vec{\nabla}] \vec{v}(t, \vec{r}) \right] = -\vec{\nabla} \mathcal{P}(t, \vec{r}) + \eta \vec{\nabla}^2 \vec{v}(t, \vec{r})$$

Divide lengths, flow velocity & pressure by typical values (depend on the fluid and flow under consideration!)

➡ yields dimensionless equation

$$\partial_{t^*} \vec{v}^*(t^*, \vec{r}^*) + [\vec{v}^*(t^*, \vec{r}^*) \cdot \vec{\nabla}^*] \vec{v}^*(t^*, \vec{r}^*) = -\frac{\vec{\nabla}^* \mathcal{P}^*(t^*, \vec{r}^*)}{\rho} + \frac{\eta}{\rho v_c L_c} \vec{\nabla}^{*2} \vec{v}^*(t^*, \vec{r}^*)$$

Model of a continuous medium

a second important dimensionless number

Write down the Navier–Stokes equation in the simpler case $\vec{\nabla} \cdot \vec{v} = 0$ & in the absence of volume forces:

$$\rho(t, \vec{r}) \left[\partial_t \vec{v}(t, \vec{r}) + [\vec{v}(t, \vec{r}) \cdot \vec{\nabla}] \vec{v}(t, \vec{r}) \right] = -\vec{\nabla} \mathcal{P}(t, \vec{r}) + \eta \vec{\nabla}^2 \vec{v}(t, \vec{r})$$

Divide lengths, flow velocity & pressure by typical values (depend on the fluid and flow under consideration!)

➡ yields dimensionless equation

$$\partial_t \vec{v} + (\vec{v} \cdot \vec{\nabla}) \vec{v} = -\frac{\vec{\nabla} \mathcal{P}}{\rho} + \frac{\eta}{\rho v_c L_c} \vec{\nabla}^2 \vec{v}$$

involving the

$$\text{Reynolds number } \text{Re} \equiv \frac{\rho v_c L_c}{\eta}$$

Model of a continuous medium

a second important dimensionless number

The

$$\text{Reynolds number } Re \equiv \frac{\rho v_c L_c}{\eta}$$

measures the importance of viscous effects in the flow:

- for $Re \ll 1$: viscous flow
- for $Re \gg 1$: inviscid (“ideal”) flow...
 - ➔ You may probably describe the fluid as perfect (not everywhere...)

Non-relativistic fluid dynamics

The dynamical equations of motion

Invoke the most basic laws of physics: **conservation equations!**

- mass / particle number conservation (equivalent since $\rho = nm$)
- momentum conservation (or more generally, Newton's 2nd law)
- **energy conservation**

each of which are expressed locally.

for a **perfect fluid** (I omit the variables and drop the volume forces...):

$$\underbrace{\partial_t \left(e + \frac{1}{2} \rho \vec{v}^2 \right)}_{\text{energy density}} + \underbrace{\vec{\nabla} \cdot \left[\left(e + \mathcal{P} + \frac{1}{2} \rho \vec{v}^2 \right) \vec{v} \right]}_{\text{energy flux density}} = 0$$

component-wise:

$$\partial_t \left(e + \frac{1}{2} \rho \vec{v}^2 \right) + \partial_i \left[\left(e + \mathcal{P} + \frac{1}{2} \rho \vec{v}^2 \right) v^i \right] = 0$$

Non-relativistic fluid dynamics

The dynamical equations of motion

Invoke the most basic laws of physics: **conservation equations!**

- mass / particle number conservation (equivalent since $\rho = nm$)
- momentum conservation (or more generally, Newton's 2nd law)
- **energy conservation**

each of which are expressed locally.

for a **Newtonian fluid** (I omit the variables and drop the volume forces...):

$$\partial_t \left(e + \frac{1}{2} \rho \vec{v}^2 \right) + \vec{\nabla} \cdot \left\{ \begin{aligned} & \left(e + \mathcal{P} + \frac{1}{2} \rho \vec{v}^2 \right) \vec{v} - \kappa \vec{\nabla} T \\ & - \left[\zeta - \frac{2\eta}{3} \right] (\vec{\nabla} \cdot \vec{v}) \vec{v} \\ & - \eta \left[(\vec{v} \cdot \vec{\nabla}) \vec{v} + \vec{\nabla} \left(\frac{\vec{v}^2}{2} \right) \right] \end{aligned} \right\} = 0$$

energy flux density:

Non-relativistic fluid dynamics

The dynamical equations of motion

Invoke the most basic laws of physics: **conservation equations!**

- mass / particle number conservation (equivalent since $\rho = nm$)
- momentum conservation (or more generally, Newton's 2nd law)
- **energy conservation**

each of which are expressed locally.

for a **Newtonian fluid** (I omit the variables and drop the volume forces...):

$$\partial_t \left(e + \frac{1}{2} \rho \vec{v}^2 \right) + \vec{\nabla} \cdot \left\{ \left(e + \mathcal{P} + \frac{1}{2} \rho \vec{v}^2 \right) \vec{v} - \kappa \vec{\nabla} T \right\} = 0$$

heat transport
 κ heat conductivity

diffusive energy transport by the viscous forces

$$\left\{ \begin{array}{l} - \left[\zeta - \frac{2\eta}{3} \right] (\vec{\nabla} \cdot \vec{v}) \vec{v} \\ - \eta \left[(\vec{v} \cdot \vec{\nabla}) \vec{v} + \vec{\nabla} \left(\frac{\vec{v}^2}{2} \right) \right] \end{array} \right\} = 0$$



Non-relativistic fluid dynamics

dynamical variables and equations

A fluid is characterized at each time and position by its

- mass density $\rho(t, \vec{r})$ / particle number $n(t, \vec{r})$ (equivalent!)
- pressure $\mathcal{P}(t, \vec{r})$
- local flow velocity $\vec{v}(t, \vec{r})$
- energy density $e(t, \vec{r})$

and possibly transport coefficients ($\eta, \zeta, \kappa\dots$): material properties!

👉 6 dynamical fields

These are governed by local expressions of conservation equations

- mass / particle number conservation
- momentum conservation
- energy conservation

👉 5 equations only



Non-relativistic fluid dynamics

dynamical variables and equations

6 dynamical fields – $\rho(t, \vec{r})$ or $n(t, \vec{r})$, $\vec{v}(t, \vec{r})$, $\mathcal{P}(t, \vec{r})$, and $e(t, \vec{r})$ – yet only 5 coupled (conservation) equations relating them to each other.

👉 one more equation needed!

- One possible easy way out:

only investigate fluid motions with a given kinematic constraint

👉 steady flows ($\partial_t = 0$), incompressible flows ($\vec{\nabla} \cdot \vec{v} = 0$), irrotational / potential flows ($\vec{\nabla} \times \vec{v} = \vec{0}$: no vorticity)...

Nature is not always that nice!

- More general, yet not innocent:

There exists a relation between internal energy density, pressure, and particle number, “the” equation of state (EoS).

[= a combination of the thermal & mechanical EoS $e(n, T)$ & $\mathcal{P}(n, T)$]

Non-relativistic fluid dynamics

dynamical variables and equations

An **equation of state** is indeed a relation between e , \mathcal{P} & n or ρ .

Yet its use presupposes that the fluid is at **thermodynamic equilibrium** (or more precisely, at **local thermodynamic equilibrium** at each point & instant).

👉 **strong assumption!**

Actually already hidden in the **transport coefficients** (η , ζ , $\kappa\dots$):

- material properties—like the **equation(s) of state**;
- that quantify dissipative currents describing the linear response of the system to (small) departures from **thermodynamic equilibrium**.

👉 are well-defined close to **thermodynamic equilibrium**.

But now, we may use the whole bunch of thermodynamic relations.

Thermodynamics

Differential of internal energy U :

$$dU = -\mathcal{P} d\mathcal{V} + T dS + \mu dN$$

\mathcal{P} pressure, \mathcal{V} volume, T temperature, S entropy, μ chemical potential; N is the number of particles.

➡ this number is not conserved in a relativistic system: should be replaced by a conserved quantum number (e.g., baryon number).

➡ In a relativistic system, U also includes the mass energy of the constituents.

Internal energy:
$$U = -\mathcal{P}\mathcal{V} + TS + \mu N \quad (1)$$

Gibbs–Duhem relation:
$$\mathcal{V} d\mathcal{P} = S dT + N d\mu$$

Thermodynamics

In fluid dynamics, the useful quantities are rather the densities:

- internal energy density $e \equiv U/\mathcal{V}$,
- entropy density $s \equiv S/\mathcal{V}$,
- (baryon) number density $n \equiv N/\mathcal{V}$.

👉 Eq.(1) gives

$$e = -\mathcal{P} + T s + \mu n$$

Gibbs–Duhem becomes

$$d\mathcal{P} = s dT + n d\mu$$

leading to:

$$de = T ds + \mu dn$$



Thermodynamics and fluid dynamics

Using the local Gibbs–Duhem relation $d\mathcal{P} = s dT + n d\mu$, one can study the behavior of entropy in moving fluids:

- in perfect fluids, the continuity equation, Euler equation, & energy conservation equation automatically lead to entropy conservation

$$\partial_t s(t, \vec{r}) + \vec{\nabla} \cdot [s(t, \vec{r}) \vec{v}(t, \vec{r})] = 0$$

- in turn, in Newtonian fluids, the continuity, Navier–Stokes, & energy conservation equations lead, if the transport coefficients η , ζ , κ are taken to be positive, to the production of entropy

$$\partial_t s(t, \vec{r}) + \vec{\nabla} \cdot [s(t, \vec{r}) \vec{v}(t, \vec{r})] \geq 0$$

which makes sense, since these coefficients characterize dissipative currents.

Non-relativistic fluid dynamics

... describes the motion of **continuous media** in **local thermodynamic equilibrium** at each t & \vec{r} , using a set of 6 equations:

- 5 dynamical relations, expressing the local conservations of mass (or particle number), momentum, & energy
 - ➡ take different forms in perfect / 1st-order / 2nd-order hydro
- and an **equation of state**.

These equations govern the coupled evolutions of

- **mass density ρ** (or equivalently **particle number density n**),
- **internal energy density e ,**
- **pressure \mathcal{P} ,**
- **flow velocity \vec{v} .**

Besides its equation of state, the fluid is characterized by **transport coefficients** ($\eta, \zeta, \kappa \dots$).

Elements of fluid dynamics for the modeling of heavy-ion collisions

Lecture I:

- Overview on the dynamics of relativistic perfect fluids

phenomenological approach

- reminder(?) on non-relativistic fluid dynamics (“hydrodynamics”)
- fundamental equations of perfect relativistic fluid dynamics
- an example of solution
- Application of perfect relativistic fluid dynamics to the description of high-energy nucleus-nucleus collisions
- Beyond perfect relativistic fluid dynamics

~~Non-~~Relativistic fluid dynamics

... describes the motion of continuous media in local thermodynamic equilibrium at each t & \vec{r} , using a set of ~~6 equations~~: $5 + N_f$ equations

- ~~5 dynamical relations~~, $4 + N_f$ dynamical relations, expressing the local conservations of mass (or ~~particle number~~ quantum numbers), momentum, & energy
 - ➔ take different forms in perfect / 1st-order / 2nd-order hydro
- and an equation of state.

These equations govern the coupled evolutions of

- ~~mass density ρ~~ (or equivalently ~~particle number density n~~ quantum densities n_a),
- internal energy density e ,
- pressure \mathcal{P} ,
- flow velocity \vec{v} . “repackaged” within a 4-velocity

Besides its equation of state, the fluid is characterized by transport coefficients ($\eta, \zeta, \kappa \dots$).



Relativistic fluid dynamics

dynamical variables and equations

A relativistic fluid is a continuous medium characterized by currents:

- a **quantum number 4-current** $N_a(x)$, with components $N_a^\mu(x)$, for each conserved quantum number a , such that (in Minkowski coordinates)
 - $N_a^0(x)$ is the local **density of quantum number** a , and
 - the $N_a^i(x)$ are the components of the **local flux density of** a ;
- an **energy-momentum tensor** $T(x)$, with components $T^{\mu\nu}(x)$, such that
 - $T^{00}(x)$ is the local **energy density**;
 - $T^{0j}(x)$ is the **density** of the j^{th} component **of momentum**;
 - the $T^{i0}(x)$ are the components of the **energy flux density**;
 - the $T^{ij}(x)$ are the components of the **momentum flux-density**.

Greek resp. Latin indices run from 0 resp. 1 to 3.

Relativistic fluid dynamics

dynamical variables and equations

A relativistic fluid is a continuous medium characterized by currents:

- a **quantum number 4-current** $N_a(x)$, with components $N_a^\mu(x)$, for each conserved quantum number a , whose **conservation equation** reads

$$\partial_\mu N_a^\mu(x) = 0$$

- an **energy-momentum tensor** $T(x)$, with components $T^{\mu\nu}(x)$, whose **conservation equation** reads

$$\partial_\mu T^{\mu\nu}(x) = 0$$

➡ take different **forms** in perfect / 1st-order / 2nd-order hydro

Rem.: in non-Minkowski coordinates, replace partial by covariant derivatives: $\partial_\mu \rightarrow d_\mu$

Relativistic perfect fluid dynamics

In **perfect / ideal** fluids:

... one can at each point x find a reference frame $LR(x)$, such that an observer at rest in $LR(x)$ sees the instantaneous local properties of the fluid as **isotropic**, i.e. (in Minkowski coordinates)

- the spatial components of every **quantum number 4-current** $N_a(x)$ vanish in $LR(x)$:

$$N_a^\mu(x) \Big|_{LR(x)} = \begin{pmatrix} n_a(x) \\ \vec{0} \end{pmatrix}$$

- in the **energy-momentum tensor** $T(x)$, all $T^{i0}(x)$ and $T^{0j}(x)$ vanish in $LR(x)$, while $T^{ij}(x)$ is diagonal:

$$T^{\mu\nu}(x) \Big|_{LR(x)} = \begin{pmatrix} \epsilon(x) & 0 & 0 & 0 \\ 0 & \mathcal{P}(x) & 0 & 0 \\ 0 & 0 & \mathcal{P}(x) & 0 \\ 0 & 0 & 0 & \mathcal{P}(x) \end{pmatrix}$$

Relativistic perfect fluid dynamics

In **perfect / ideal** fluids:

... one can at each point x find a reference frame $LR(x)$, such that an observer at rest in $LR(x)$ sees the instantaneous local properties of the fluid as **isotropic**.

The 4-velocity $u(x)$ of that observer with respect to an observer at rest in another reference frame \mathcal{R} defines the **flow 4-velocity** of the fluid w.r.t. \mathcal{R} .

That is, the **flow 4-velocity** $u(x)$ — which is timelike and normalized to -1 , i.e. $[u(x)]^2 = -1$ — has in the “**local rest frame**” $LR(x)$ at x the Minkowski components

$$u^\mu(x) \Big|_{LR(x)} = \begin{pmatrix} 1 \\ \vec{0} \end{pmatrix}$$

As is now clear, the metric with signature $(-,+,+,+)$ will be used.

Relativistic perfect fluid dynamics

In **perfect / ideal** fluids:

... one can at each point x find a reference frame $LR(x)$, such that an observer at rest in $LR(x)$ sees the instantaneous local properties of the fluid as **isotropic**.

The 4-velocity $u(x)$ of that observer with respect to an observer at rest in another reference frame \mathcal{R} defines the **flow 4-velocity** of the fluid w.r.t. \mathcal{R} .

Denoting by $\vec{v}(x)$ the corresponding 3-velocity w.r.t. \mathcal{R} and by $\gamma(x)$ the associated Lorentz factor, the components of the **4-velocity** in \mathcal{R} read

$$u^\mu(x)|_{\mathcal{R}} = \begin{pmatrix} \gamma(x) \\ \gamma(x)\vec{v}(x) \end{pmatrix} \quad \text{with} \quad \gamma(x) \equiv \frac{1}{\sqrt{1 - \vec{v}(x)^2}}$$



Relativistic perfect fluid dynamics

In the local frame LR(x) the **quantum number 4-current** $N_a(x)$ and **energy-momentum tensor** $T(x)$, have the simple expressions

$$N_a^\mu(x)|_{\text{LR}(x)} = \begin{pmatrix} n_a(x) \\ \vec{0} \end{pmatrix} \quad T^{\mu\nu}(x)|_{\text{LR}(x)} = \begin{pmatrix} \epsilon(x) & 0 & 0 & 0 \\ 0 & \mathcal{P}(x) & 0 & 0 \\ 0 & 0 & \mathcal{P}(x) & 0 \\ 0 & 0 & 0 & \mathcal{P}(x) \end{pmatrix}$$

involving local densities $n_a(x)$ for quantum number a & $\epsilon(x)$ for energy, and pressure $\mathcal{P}(x)$.

In an arbitrary reference frame and system of coordinates, they are given by

$$N_a^\mu(x) = n_a(x)u^\mu(x)$$

$$T^{\mu\nu}(x) = [\epsilon(x) + \mathcal{P}(x)]u^\mu(x)u^\nu(x) + \mathcal{P}(x)g^{\mu\nu}(x)$$

(identities between two 4-vectors / tensors valid in one reference frame, thus in any.)

Relativistic perfect fluid dynamics

The components of the **quantum number 4-current** $N_a(x)$ and **energy-momentum tensor** $T(x)$ of a **perfect fluid** are given by

$$N_a^\mu(x) = n_a(x)u^\mu(x)$$

$$T^{\mu\nu}(x) = [\epsilon(x) + \mathcal{P}(x)]u^\mu(x)u^\nu(x) + \mathcal{P}(x)g^{\mu\nu}(x)$$

in terms of the **flow 4-velocity** $u(x)$.

Introducing the tensor $\Delta^{\mu\nu}(x) \equiv g^{\mu\nu}(x) + u^\mu(x)u^\nu(x)$, which projects on the 3-space orthogonal to the 4-velocity **[check!]**, the latter may be recast as

$$T^{\mu\nu}(x) = \epsilon(x)u^\mu(x)u^\nu(x) + \mathcal{P}(x)\Delta^{\mu\nu}(x)$$

Relativistic perfect fluid dynamics

The components of the **quantum number 4-current** $N_a(\mathbf{x})$ and **energy-momentum tensor** $T(\mathbf{x})$ of a **perfect fluid** are given by

$$N_a^\mu(\mathbf{x}) = n_a(\mathbf{x})u^\mu(\mathbf{x})$$

$$T^{\mu\nu}(\mathbf{x}) = \epsilon(\mathbf{x})u^\mu(\mathbf{x})u^\nu(\mathbf{x}) + \mathcal{P}(\mathbf{x})\Delta^{\mu\nu}(\mathbf{x})$$

in terms of the **flow 4-velocity** $u(\mathbf{x})$ and the projector orthogonal to it.

One easily checks **[exercise!]** the identities

$$n_a(\mathbf{x}) = \frac{N_a^\mu(\mathbf{x})u_\mu(\mathbf{x})}{u^\nu(\mathbf{x})u_\nu(\mathbf{x})}, \quad \epsilon(\mathbf{x}) = u_\mu(\mathbf{x})T^{\mu\nu}(\mathbf{x})u_\nu(\mathbf{x}), \quad \mathcal{P}(\mathbf{x}) = \frac{1}{3}\Delta_{\mu\nu}(\mathbf{x})T^{\mu\nu}(\mathbf{x})$$

valid in reference frame and system of coordinates.

These relations show that $n_a(\mathbf{x})$, $\epsilon(\mathbf{x})$, $\mathcal{P}(\mathbf{x})$ are scalar fields.

Relativistic perfect fluid dynamics

dynamical variables and equations

In a **perfect** relativistic fluid the conserved currents are:

- N_f **quantum number 4-currents** $N_a(x)$, with components $N_a^\mu(x)$, whose **conservation equation** read

$$\partial_\mu N_a^\mu(x) = 0$$

with

$$N_a^\mu(x) = n_a(x) u^\mu(x)$$

- the **energy-momentum tensor** $T(x)$, with components $T^{\mu\nu}(x)$, whose **conservation equation** reads

$$\partial_\mu T^{\mu\nu}(x) = 0$$

with

$$T^{\mu\nu}(x) = \epsilon(x) u^\mu(x) u^\nu(x) + \mathcal{P}(x) \Delta^{\mu\nu}(x)$$

5 (= $\epsilon(x)$, $\mathcal{P}(x)$, only 3 components of $u(x)$) + N_f fields, 4 + N_f equations

☞ equation of state to close the system of equations!

Relativistic perfect fluid dynamics

a quick example

Consider a flow with small velocity.

To first order in the latter:

$$T^{\mu\nu} = \begin{pmatrix} \epsilon & (\epsilon + \mathcal{P})v^1 & (\epsilon + \mathcal{P})v^2 & (\epsilon + \mathcal{P})v^3 \\ (\epsilon + \mathcal{P})v^1 & \mathcal{P} & 0 & 0 \\ (\epsilon + \mathcal{P})v^2 & 0 & \mathcal{P} & 0 \\ (\epsilon + \mathcal{P})v^3 & 0 & 0 & \mathcal{P} \end{pmatrix}$$

so that the **energy-momentum conservation equation** reads

$$\partial_\mu T^{\mu 0} = 0 \qquad \partial_t \epsilon + \vec{\nabla} \cdot [(\epsilon + \mathcal{P})\vec{v}] = 0 \qquad (2)$$

$$\partial_\mu T^{\mu j} = 0 \qquad \partial_t [(\epsilon + \mathcal{P})\vec{v}] + \vec{\nabla} \mathcal{P} = \vec{0} \qquad (3)$$

Relativistic perfect fluid dynamics

a quick example

Consider small adiabatic perturbation (sound wave!) of a uniform and steady flow:

$$\begin{cases} \epsilon(\mathbf{x}) = \epsilon_0 + \delta\epsilon(\mathbf{x}) \\ \mathcal{P}(\mathbf{x}) = \mathcal{P}_0 + \delta\mathcal{P}(\mathbf{x}) \end{cases}$$

Linearizing the equations of motion (2,3) yields:

• from (2):
$$\partial_t(\delta\epsilon) + (\epsilon_0 + \mathcal{P}_0)\vec{\nabla} \cdot \vec{v} = 0 \quad (4)$$

• from (3):
$$(\epsilon_0 + \mathcal{P}_0)\partial_t\vec{v} + \vec{\nabla}\delta\mathcal{P} = \vec{0} \quad (5)$$

Defining $c_s^2 \equiv \left(\frac{\partial\mathcal{P}}{\partial\epsilon}\right)_{\frac{s}{n}}$, eqs. (4) & (5) lead to

$$\partial_t^2(\delta\epsilon) - c_s^2\vec{\nabla}^2(\delta\epsilon) = 0$$

wave equation, c_s speed of sound.

☞ equation of state $\mathcal{P}(\epsilon)$!

Relativistic perfect fluid dynamics

“equation of state”

Since the **speed of sound** c_s is given by the relation

$$c_s^2 \equiv \left(\frac{\partial \mathcal{P}}{\partial \epsilon} \right)_{\frac{s}{n}}$$

the **equation of state** when there are no relevant conserved quantum number is precisely the relation between **pressure** and **energy density**.

Simple examples (for analytical calculations) are

- for massless particles (living in 1+3 dimensions): $\epsilon = 3\mathcal{P}$
- massive particles (in cosmology): $\mathcal{P} = 0$ (“dust”)
- “vacuum” (in cosmology): $\mathcal{P} = -\epsilon$

For heavy-ion collisions, compact astrophysical objects ($n \neq 0$), precision cosmology: more complicated forms!

Elements of fluid dynamics for the modeling of heavy-ion collisions

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Relativistic perfect fluid dynamics

an example of solution

The dynamical equations of **perfect** relativistic fluid read

- N_f times $\partial_\mu N_a^\mu(x) = 0$ with $N_a^\mu(x) = n_a(x)u^\mu(x)$
- and $\partial_\mu T^{\mu\nu}(x) = 0$ with $T^{\mu\nu}(x) = \epsilon(x)u^\mu(x)u^\nu(x) + \mathcal{P}(x)\Delta^{\mu\nu}(x)$

Projecting the energy-momentum conservation equation parallel and perpendicular to the 4-velocity yields:

$$u^\mu(x)\partial_\mu\epsilon(x) + [\epsilon(x) + \mathcal{P}(x)]\partial_\mu u^\mu(x) = 0$$

$$[\epsilon(x) + \mathcal{P}(x)]u^\mu(x)\partial_\mu u^\nu(x) + \Delta^{\mu\nu}(x)\partial_\mu\mathcal{P}(x) = 0$$

Convenient notation: $\nabla^\nu \equiv \Delta^{\mu\nu}(x)\partial_\mu$

Rem.: in non-Minkowski coordinates, replace partial by covariant derivatives: $\partial_\mu \rightarrow d_\mu$

Relativistic perfect fluid dynamics

an example of solution

The dynamical equations of **perfect** relativistic fluid read

- N_f times $\partial_\mu N_a^\mu(x) = 0$ with $N_a^\mu(x) = n_a(x)u^\mu(x)$
- and $\partial_\mu T^{\mu\nu}(x) = 0$ with $T^{\mu\nu}(x) = \epsilon(x)u^\mu(x)u^\nu(x) + \mathcal{P}(x)\Delta^{\mu\nu}(x)$

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Convenient notation: $\nabla^\nu \equiv \Delta^{\mu\nu}(x)\partial_\mu$

Rem.: in non-Minkowski coordinates, replace partial by covariant derivatives: $\partial_\mu \rightarrow d_\mu$

An example of relativistic flow: “Bjorken flow”

Quantum-number-free perfect fluid, $n_a(x) = 0$
in one-dimensional motion along the z -axis with the 3-velocity $v^z = \frac{z}{t}$
for $z < ct$ and $t > t_0$.

First(?) discussed by R.Hwa (1974); made ~~popular~~ **famous** by J.D.Bjorken (1983)

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Highly relativistic nucleus-nucleus collisions: The central rapidity region

J. D. Bjorken

*Fermi National Accelerator Laboratory, * P.O. Box 500, Batavia, Illinois 60510*

7. Highly Relativistic Nucleus-Nucleus Collisions: The Central Rapidity Region

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Bjorken flow

One-dimensional flow along the z -axis with the 3-velocity $v^z = \frac{z}{t}$ for $z < ct$ and $t > t_0$.

👉 4-velocity* $u^\mu(x) = \begin{pmatrix} \gamma(x) \\ \gamma(x)v^z(x) \end{pmatrix}$ with $\gamma(x) = \frac{1}{\sqrt{1 - v^z(x)^2}} = \frac{t}{\sqrt{t^2 - z^2}}$

*only the non-trivial components are shown

Bjorken flow

One-dimensional flow along the z -axis with the 3-velocity $v^z = \frac{z}{t}$ for $z < ct$ and $t > t_0$.

👉 4-velocity* $u^\mu(x) = \begin{pmatrix} t \\ \sqrt{t^2 - z^2} \\ z \\ \sqrt{t^2 - z^2} \end{pmatrix}$

*only the non-trivial components are shown

Bjorken flow

One-dimensional flow along the z -axis with the 3-velocity $v^z = \frac{z}{t}$ for $z < ct$ and $t > t_0$.

👉 4-velocity* $u^\mu(x) = \begin{pmatrix} t \\ \sqrt{t^2 - z^2} \\ z \\ \sqrt{t^2 - z^2} \end{pmatrix} = \begin{pmatrix} \cosh \varsigma \\ \sinh \varsigma \end{pmatrix}$

Milne coordinates $\begin{cases} \tau \equiv \sqrt{t^2 - z^2} \\ \varsigma \equiv \frac{1}{2} \log \frac{t+z}{t-z} \end{cases} \Leftrightarrow \begin{cases} t = \tau \cosh \varsigma \\ z = \tau \sinh \varsigma \end{cases}$

*only the non-trivial components are shown

Bjorken flow

One-dimensional flow along the z -axis with the 3-velocity $v^z = \frac{z}{t}$ for $z < ct$ and $t > t_0$.

👉 4-velocity* $u^\mu(x) = \begin{pmatrix} t \\ \sqrt{t^2 - z^2} \\ z \\ \sqrt{t^2 - z^2} \end{pmatrix} = \begin{pmatrix} \cosh \varsigma \\ \sinh \varsigma \end{pmatrix}$

Milne coordinates $\begin{cases} \tau \equiv \sqrt{t^2 - z^2} \\ \varsigma \equiv \frac{1}{2} \log \frac{t+z}{t-z} \end{cases} \Leftrightarrow \begin{cases} t = \tau \cosh \varsigma \\ z = \tau \sinh \varsigma \end{cases}$

Two possibilities:

- work directly in Milne coordinates $(x^{0'}, x^{1'}) = (\tau, \varsigma)$ 👉 $u^{\mu'}(x) = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$
- stay with Minkowski coordinates 👉 simple derivatives

*only the non-trivial components are shown

Bjorken flow

$$\begin{cases} \tau \equiv \sqrt{t^2 - z^2} \\ \varsigma \equiv \frac{1}{2} \log \frac{t+z}{t-z} \end{cases} \Leftrightarrow \begin{cases} t = \tau \cosh \varsigma \\ z = \tau \sinh \varsigma \end{cases}$$

One easily shows [check!] that the equation of motion “along $u(x)$ ”

$$u^\mu(x) \partial_\mu \epsilon(x) + [\epsilon(x) + \mathcal{P}(x)] \partial_\mu u^\mu(x) = 0$$

becomes

$$\partial_\tau \epsilon(x) + \frac{\epsilon(x) + \mathcal{P}(x)}{\tau} = 0$$

or equivalently

$$\partial_\tau [\tau \epsilon(x)] = -\mathcal{P}(x)$$

which simply relates the change in the energy in a comoving volume (proportional to τ) to the work of pressure forces...

Bjorken flow

$$\begin{cases} \tau \equiv \sqrt{t^2 - z^2} \\ \varsigma \equiv \frac{1}{2} \log \frac{t+z}{t-z} \end{cases} \Leftrightarrow \begin{cases} t = \tau \cosh \varsigma \\ z = \tau \sinh \varsigma \end{cases}$$

In turn, the equation of motion “perpendicular to $u(\mathbf{x})$ ”

$$[\epsilon(\mathbf{x}) + \mathcal{P}(\mathbf{x})] u^\mu(\mathbf{x}) \partial_\mu u^\nu(\mathbf{x}) + \nabla^\nu \mathcal{P}(\mathbf{x}) = 0$$

yields [check!]

$$\partial_\varsigma \mathcal{P}(\mathbf{x}) = 0$$

i.e. pressure – and, invoking the equation of state, energy density – is independent of space-time rapidity.

👉 boost invariance!

Bjorken flow

Coming back to
$$\partial_\tau \epsilon(x) + \frac{\epsilon(x) + \mathcal{P}(x)}{\tau} = 0$$

inserting the equation of state $\mathcal{P}(x) = c_s(x)^2 \epsilon(x)$ yields

$$\partial_\tau \epsilon(x) + [1 + c_s(x)^2] \frac{\epsilon(x)}{\tau} = 0$$

If the speed of sound is constant, this leads to

$$\epsilon(x) \propto \frac{1}{\tau^{1+c_s^2}} \qquad \mathcal{P}(x) \propto \frac{1}{\tau^{1+c_s^2}}$$

Bjorken flow

In turn, the entropy conservation equation $\partial_\mu [s(x)u^\mu(x)] = 0$ becomes

$$\partial_\tau s(x) + \frac{s(x)}{\tau} = 0$$

leading at once to

$$s(x) \propto \frac{1}{\tau}$$

Using now $\epsilon(x) \propto \frac{1}{\tau^{1+c_s^2}}$, $\mathcal{P}(x) \propto \frac{1}{\tau^{1+c_s^2}}$ and the relation $\epsilon + \mathcal{P} = Ts$, one arrives at

$$T(x) \propto \frac{1}{\tau c_s^2}$$

Bjorken flow

We have found $\epsilon(x) \propto \frac{1}{\tau^{1+c_s^2}}$, $\mathcal{P}(x) \propto \frac{1}{\tau^{1+c_s^2}}$, $s(x) \propto \frac{1}{\tau}$

and indirectly $T(x) \propto \frac{1}{\tau^{c_s^2}}$

For an ultrarelativistic gas $\epsilon \propto T^4$ (Stefan-Boltzmann!), $\mathcal{P} \propto T^4$
 $s \propto T^3$ (remember $\epsilon + \mathcal{P} = T s$) and $c_s^2 = \frac{1}{3}$... Everything is OK!