

Ideal Hydrodynamics: Tensor Analysis

- Given a $T^{\mu\nu}$, there is a frame where $T^{0i} = 0$.
Denote this Local Rest Frame (LRF) by $u^\mu = (\gamma, \gamma\mathbf{v})$ and $u^2 = -1$. $u^\mu = (1, \mathbf{0})$. $g^{\mu\nu} = (-, +, +, +)$.
- In the LRF the stress energy tensor in equilibrium is

$$T^{\mu\nu} = \begin{matrix} & t & x & y & z \\ \begin{matrix} t \\ x \\ y \\ z \end{matrix} & \begin{pmatrix} e & 0 & 0 & 0 \\ 0 & p & 0 & 0 \\ 0 & 0 & p & 0 \\ 0 & 0 & 0 & p \end{pmatrix} \end{matrix} \quad \text{and} \quad N^\mu = (n, \mathbf{0})$$

- $T^{\mu\nu}$ must be a function of $u^\mu u^\nu$ and $g^{\mu\nu}$.
Can also use the projector $\Delta^{\mu\nu}$ and $u^\mu u^\nu$:

$$\Delta^{\mu\nu} = g^{\mu\nu} + u^\mu u^\nu = \text{diag}(0, 1, 1, 1)$$

Verify: $\Delta^{\mu\nu} u_\nu = 0$ and $\Delta \cdot \Delta = \Delta$

- The general vector and tensor having this form:

$$\begin{aligned} T^{\mu\nu} &= e u^\mu u^\nu + p \Delta^{\mu\nu} \\ N^\mu &= n u^\mu \end{aligned}$$

Ideal Hydrodynamics: Physics

- Equations of motion:

$$\begin{aligned}\partial_\mu T^{\mu\nu} &= \partial_\mu (e u^\mu u^\nu + p \Delta^{\mu\nu}) = 0 \\ \partial_\mu N^\mu &= \partial_\mu (n u^\mu) = 0\end{aligned}$$

- Equation of State (EoS): $p(e, n)$
- Five Equations of Motion (T^{00}, T^{0i}, N^0) and Five unknowns e, \mathbf{v}, n .

To interpret these EOM let us write them in the LRF:

$$\begin{aligned}\partial_t T^{00} \rightarrow \partial_t e &= -(e + p) \partial_i v^i \\ \partial_t T^{0i} \rightarrow \partial_t v_i &= -\frac{1}{e + p} \partial_i p \\ \partial_t N^0 \rightarrow \partial_t n &= -n \partial_i v^i\end{aligned}$$

- The acceleration is proportional to pressure gradients.
The “mass” is replaced by enthalpy in a relativistic theory.
- Equations of motion depend only on the gradients of pressure and enthalpy $\equiv e + p$. Independent of Bag constant.

Adiabatic Expansion:

$$\boxed{\frac{dV}{V} = dt \times \partial_i v^i} \quad \begin{aligned} \partial_t e &= -(e + p) \partial_i v^i \\ \partial_t n &= -n \partial_i v^i \end{aligned}$$

$$de = -(e + p) \frac{dV}{V} \implies d(eV) = -pdV$$

$$dn = -n \frac{dV}{V} \implies d(nV) = 0$$

Compare : $d(eV) = Td(sV) - pdV - \mu d(nV)$ and find

$$d(sV) = 0 \text{ or } \partial_\mu (su^\mu) = 0 \text{ or } u^\mu \partial_\mu (n/s) = 0$$

- The system evolves on the **Adiabatic** path, $n/s = \text{const.}$
- Important thermodynamic relations exist for this trajectory.

$$\left(\frac{dp}{de} \right)_{n/s} \equiv c_s^2$$

$$\left(\frac{ds}{de} \right)_{n/s} = \frac{s}{e + p} \quad (\text{The second law, **Verify**})$$

- Given c_s^2 , these equations can be integrated to determine the **entropy** and all other thermodynamic quantities.

Ideal Hydrodynamics: Some Notation

$$D = u^\alpha \partial_\alpha = \text{The time derivative in the rest frame}$$

$$\nabla^\mu = \Delta^{\mu\nu} \partial_\nu = \text{The spatial derivative in the rest frame}$$

Then the ideal equations of motion ($\partial_\mu T^{\mu\nu} = 0$) be written

$$\begin{aligned} De &= -(e + p) \nabla_\mu u^\mu \\ Du^\mu &= -\frac{1}{e + p} \nabla^\mu p \\ Dn &= -n \nabla_\mu u^\mu \end{aligned}$$

Verify: these equations from $\partial_\mu T^{\mu\nu} = 0$:

Use: $\partial_\mu = u_\mu D + \nabla_\mu$, $u^2 = -1$, $\Delta^{\mu\nu} u_\nu = 0$,
 $u_\mu Du^\mu = u_\mu \nabla^\alpha u^\mu = 0$.

This notation facilitates easy going back and forth between

LRF and covariant notation:

$$D \rightarrow \partial_t \quad \text{and} \quad \nabla_\mu \rightarrow \partial_i$$

Verify: Entropy conservation $D(s/n) = 0$.

Example: Entropy Conservation

$$\begin{aligned} D(s/n) &= \frac{1}{n} \left(\frac{\partial s}{\partial e} \right)_n De + \left\{ \frac{1}{n} \left(\frac{\partial s}{\partial n} \right)_e - s/n \right\} \frac{Dn}{n} \\ &= - \left[\frac{e+p}{nT} - \frac{\mu}{nT} - s/n \right] \nabla_\mu u^\mu \\ &= 0 \quad (\text{with } e+p-sT = \mu n) \end{aligned}$$

Viscous Hydrodynamics: Tensor Analysis

Consider the EOM close to the rest frame, $\mathbf{u}^i \ll 1$

• $T^{00} = e, T^{0i} = M^i = (e + p)u^i, N^0 = n$

$$\partial_t e + \partial_i M^i = 0$$

$$\partial_t M + \partial_i \tau^{ij} = 0$$

$$\partial_t n + \partial_i j_n = 0$$

Determine the form of τ^{ij} and j^i by expanding around equilibrium to first order in gradients: $\partial_i M_j, \partial_i e, \partial_i n$

Vector	$\partial^i n, \partial^i e$
Tensor	$\partial^i M^j + \partial^j M^i - \frac{2}{3} \delta^{ij} \partial_l M^l, \delta^{ij} \partial_l M^l$
Pseudo Vector	$\epsilon^{ijk} \partial_j M_k$ Needed if system is rotating

$$j_e^i = M^i \text{ (By symmetry } T^{0i} = T^{0i}\text{)}$$

$$\tau^{ij} = p \delta^{i,j} + a_0 \delta^{ij} \partial_i M^i + a_1 \left(\partial^i M^j + \partial^j M^i - \frac{2}{3} \delta^{ij} \partial_l M^l \right)$$

$$j^i = n v^i + b_0 \partial^i e + b_1 \partial^i n$$

(Aside: Statistical Mechanics with Motion)

$$\text{(Energy)} \quad dE = TdS - pdV - v_i dM^i$$

$$\text{(Partition Function)} \quad Z \propto \sum_n e^{-\frac{E_n - v_i M_n^i}{T}}$$

It is better to expand in gradients of thermodynamic conjugates to exploit Onsager's reciprocity relations:

$$\begin{aligned} ds &= \left(\frac{\partial s}{\partial e} \right)_{n, M^i} de + \left(\frac{\partial s}{\partial n} \right)_{e, M^i} dn + \left(\frac{\partial s}{\partial M^i} \right)_{e, n} dM^i \\ &= \frac{1}{T} de - \frac{\mu}{T} dn - \frac{v_i}{T} dM^i \end{aligned}$$

We use the gradients $\partial^i \frac{1}{T}$, $\partial^i \left(\frac{\mu}{T} \right)$, and $\partial^i u^j$.

(Note $\partial^i \left(\frac{u^j}{T} \right) \approx \frac{1}{T} \partial^i u^j$ since $u^i \ll 1$)

$$j_e^i = M^i + [\lambda_{ee} = 0] + \underbrace{[\lambda_{en} = 0]}$$

$$\begin{aligned} \tau^{ij} &= p\delta^{i,j} + \lambda_{MM}^L \delta_{ij} \partial_l \left(\frac{u^l}{T} \right) \\ &\quad + \lambda_{MM}^T \left(\partial^i u^j + \partial^j u^i - \frac{2}{3} \delta^{ij} \partial_l u^l \right) \end{aligned}$$

$$j_n^i = nu^i + \lambda_{nn} \partial^i \left(\frac{\mu}{T} \right) + \underbrace{\lambda_{ne} \partial^i \left(\frac{1}{T} \right)}$$

Onsager Reciprocity: $\lambda_{ne} = \lambda_{en} = 0$.

Ingredients in proof of Onsager's Reciprocity:

- Symmetry (or Anti-Symmetry) under Time reversal. Needs modification when a Magnetic field is present.
- Entropy is a maximized in equilibrium and hence is a quadratic function of e, n, m^i .
- Symmetry + Onsager are needed to fix the form of the stresses.

Boosting the results:

1. First write

$$\begin{array}{l|l} T^{\mu\nu} = T_0^{\mu\nu} + \tau^{\mu\nu} & \tau^{\mu\nu} u_\nu = 0 \quad (T^{\mu\nu} u_\nu = e u^\mu) \\ N^\mu = N_0^\mu + q^\mu & q^\nu u_\nu = 0 \quad (N^\nu u_\nu) = n \end{array}$$

2. The Spatial gradients are:

$$\nabla^\mu u^\nu, \quad \nabla^\mu T, \quad \nabla^\mu \left(\frac{\mu}{T} \right)$$

3. Expand $\tau^{\mu\nu}$ and q^μ

$$\tau^{\mu\nu} = -\eta \langle \nabla^\mu u^\nu \rangle - \sigma \Delta^{\mu\nu} \nabla_\alpha u^\alpha$$

$$q^\mu = -\kappa \left(\frac{nT}{e+p} \right)^2 \nabla^\mu \left(\frac{\mu}{T} \right) + \underbrace{[\lambda_{ne} = 0]}_{\text{red}} \partial^\mu \left(\frac{1}{T} \right)$$

Definition: $\langle \nabla^\mu u^\nu \rangle \equiv \nabla^\mu u^\nu + \nabla^\nu u^\mu - \frac{2}{3} \Delta^{\mu\nu} \nabla_\alpha u^\alpha$

Entropy production: (Ignore baryon number for simplicity)

- Definition: $T^{\mu\nu}u_\nu = eu^\mu$
- Differentiate: $\partial_\mu T^{\mu\nu}u_\nu$. Find

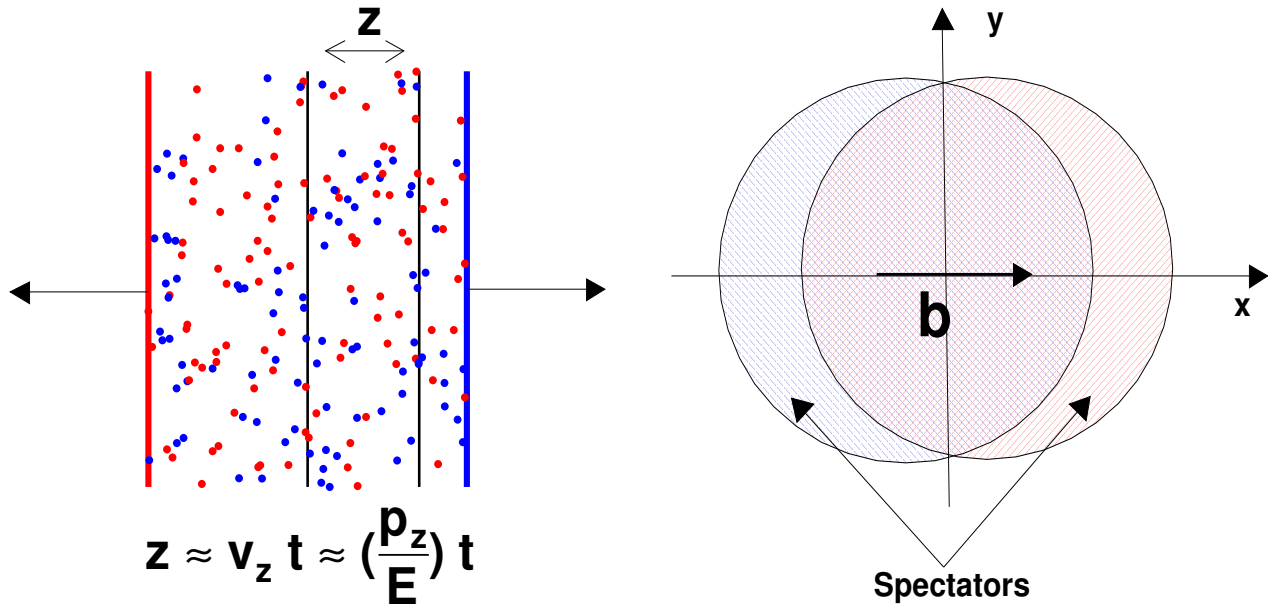
$$\underbrace{De = -(e + p)\nabla_\mu u^\mu}_{T\partial_\mu(su^\mu)} - \tau^{\mu\nu}\partial_\mu u_\nu$$

- Thermodynamic Relations: $\frac{ds}{de} = \frac{1}{T}$ and $sT = e + p$
- Put It all together: Find

$$\partial_\mu(su^\mu) = \frac{\eta}{2T} \langle \nabla^\mu u^\nu \rangle \langle \nabla_\mu u_\nu \rangle + \frac{\sigma}{T} (\nabla_\alpha u^\alpha)^2$$

- Entropy production = $\frac{1}{LT} \times$ viscous coefficients.
- Require: $\eta > 0, \sigma > 0$ and $\kappa > 0$

A View of Heavy Ion Collision: The Bjorken expansion



Define the space time rapidity and proper time:

$$\eta_s = \frac{1}{2} \log \frac{1+z/t}{1-z/t} \quad \text{and} \quad \tau = \sqrt{t^2 - z^2}$$

$$\eta_s \equiv \frac{1}{2} \log \frac{1+z/t}{1-z/t} \approx \frac{1}{2} \log \frac{1+p_z/E}{1-p_z/E} \equiv y$$

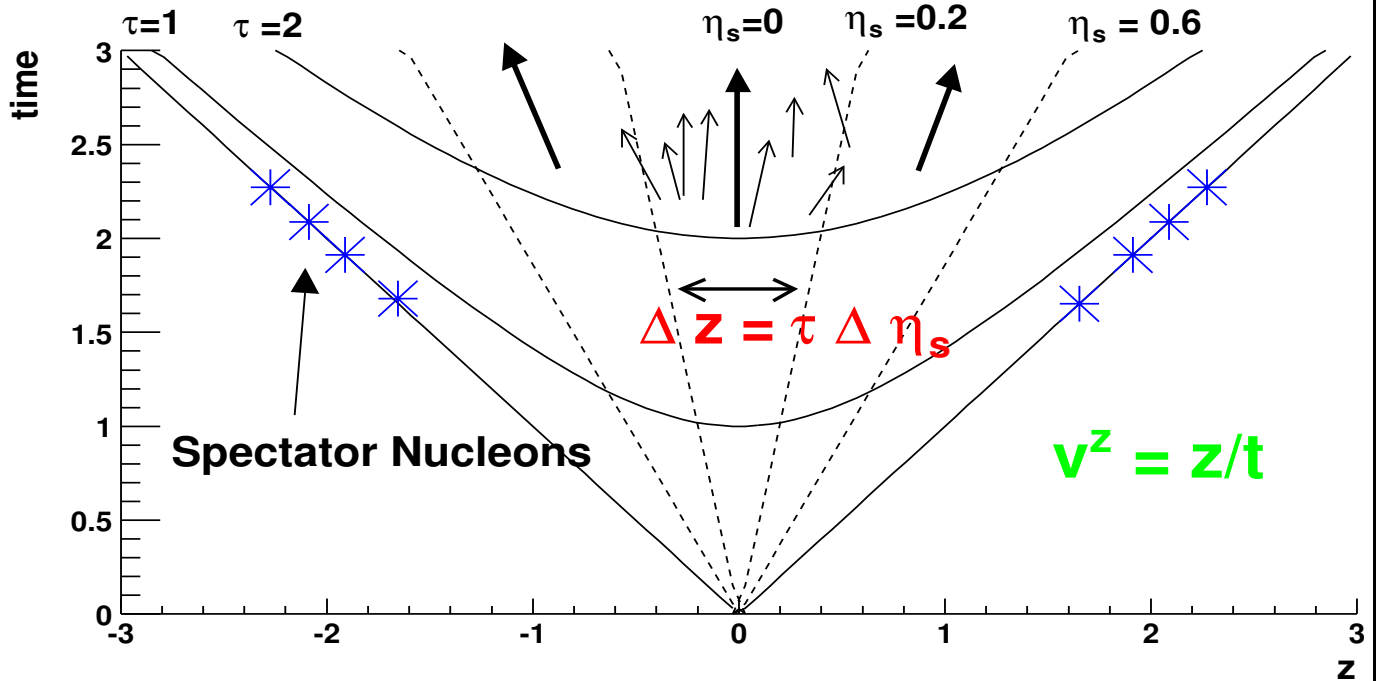
Up to smearing, all rapidities are the same in high energy collision

For hydrodynamics this means

- This means for the fluid $\langle v_z \rangle = \frac{u^z}{u^0} = z/t = \tanh(\eta_s)$. Or

$$u^z(\tau, \eta_s) = \sinh(\eta_s) \quad \text{and} \quad u^0(\tau, \eta_s) = \cosh(\eta_s)$$

- Look for solutions of $\partial_\mu T^{\mu\nu} = 0$ of this form.



Plug in $u^\mu = (u^0, u^z) = (\cosh(\eta_s), \sinh(\eta_s))$

$$\begin{array}{l|l}
 De = -(e+p)\nabla_\mu u^\mu & V = \tau (\pi R_A^2 \Delta\eta) \\
 \frac{de}{d\tau} = -(e+p) \frac{1}{\tau} & dV = d\tau (\pi R_A^2 \Delta\eta) \\
 \frac{d(\tau e)}{d\tau} = -p & \frac{1}{V} \frac{dV}{d\tau} = \frac{1}{\tau}
 \end{array}$$

- The energy per unit rapidity (τe) decreases due to the $p dV$ work in the longitudinal direction.
- The pressure is due to the thermal smearing of longitudinal velocities.

Viscosity and the Bjorken Expansion:

For a Bjorken expansion close to mid-rapidity: $v_z = z/t$

$$(\tau^{ij})_\eta = -\eta \left(\partial_i v_j + \partial_j v_i - \frac{2}{3} \delta^{ij} \partial_l v^l \right)$$

$$(\tau^{ij})_\sigma = -\sigma \delta^{ij} (\partial_l v^l)$$

The only gradient is $\partial_z v^z = \frac{1}{V} \frac{dV}{d\tau} = \frac{1}{\tau}$

$$(\tau^{ij})_\eta = \begin{matrix} & \begin{matrix} x & y & z \end{matrix} \\ \begin{matrix} x \\ y \\ z \end{matrix} & \begin{pmatrix} +\frac{2}{3} \frac{\eta}{\tau} & & \\ & +\frac{2}{3} \frac{\eta}{\tau} & \\ & & -\frac{4}{3} \frac{\eta}{\tau} \end{pmatrix} \end{matrix} \quad \text{and} \quad (\tau^{ij})_\sigma = -\frac{\sigma}{\tau} \delta^{ij}$$

The stress energy tensor is:

$$\begin{aligned} T^{ij} &= T_o^{ij} + (\tau^{ij})_\eta + (\tau^{ij})_\sigma \\ &= \begin{pmatrix} p & & \\ & p & \\ & & p \end{pmatrix} + \begin{pmatrix} \frac{2}{3} \frac{\eta - \sigma}{\tau} & & \\ & \frac{2}{3} \frac{\eta - \sigma}{\tau} & \\ & & -\frac{4}{3} \frac{\eta + \sigma}{\tau} \end{pmatrix} \end{aligned}$$

- The Longitudinal Pressure is **reduced** by $\frac{4}{3} \eta / \tau$.
- The Transverse Pressure is **increased** by $\frac{2}{3} \eta / \tau$.

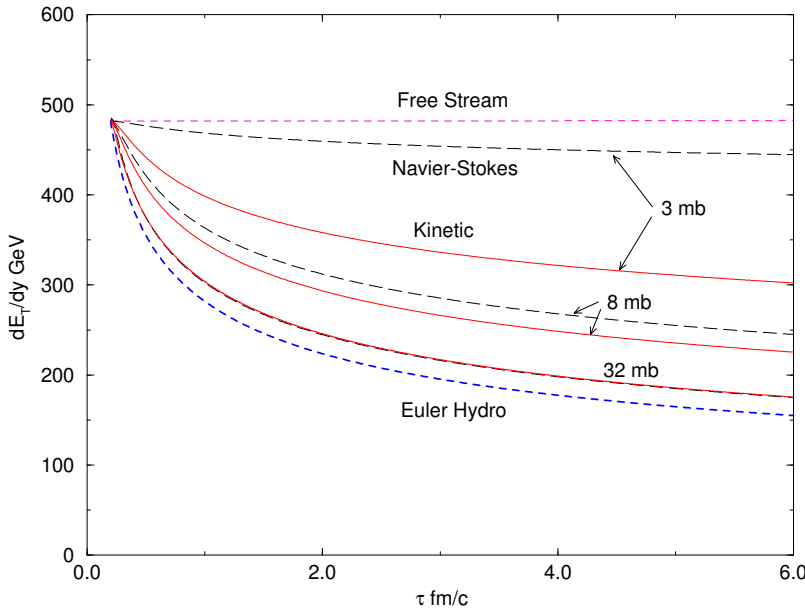
Now write down the equations of motion:

$$\underbrace{De = -(e + p)\nabla_{\mu}u^{\mu} - \tau^{\mu\nu}\partial_{\mu}u_{\nu}}_{T\partial_{\mu}(su^{\mu})} \Rightarrow \underbrace{\frac{de}{d\tau} = -\frac{e + p}{\tau}}_{T\frac{d(\tau s)}{d\tau}} + \frac{\frac{4}{3}\eta + \sigma}{\tau} \frac{1}{\tau}$$

The equations of motion are:

$$\frac{d(\tau e)}{d\tau} = - \underbrace{\left(p - \frac{\frac{4}{3}\eta + \sigma}{\tau} \right)}_{T^{zz}} \Rightarrow T \frac{d(\tau s)}{d\tau} = \frac{\frac{4}{3}\eta + \sigma}{\tau}$$

- The longitudinal pressure is reduced in the longitudinal direction. The $p dV$ work is also reduced.
- The entropy/rapidity (i.e. τs) increases as a function of time as $\frac{\frac{4}{3}\eta + \sigma}{\tau}$



$$\frac{d(\tau e)}{d\tau} = -p + \frac{4}{3}\eta/\tau$$

- For **Euler Hydro** and ideal gas: $p = \frac{1}{3}\epsilon$, $\epsilon = \epsilon_0 \left(\frac{T}{T_0}\right)^4$

$$(\tau\epsilon) = (\tau_0\epsilon_0) \left(\frac{\tau_0}{\tau}\right)^{1/3} \quad \text{and} \quad T = T_0 \left(\frac{\tau_0}{\tau}\right)^{1/3}$$

This has a simple explanation:

$$\frac{d(\tau s)}{d\tau} = 0 \quad \text{with } s \propto T^3 \quad \text{find } T \propto \frac{1}{\tau^{1/3}}$$

$$n \propto T^3 \quad \text{and} \quad \tau n = \frac{dn}{dy} = \text{Const}$$

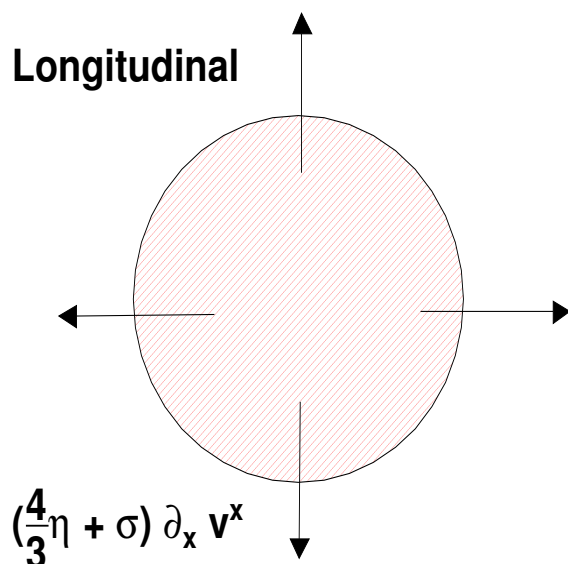
- For a **free streaming gas**: energy/rapidity is conserved $p = 0$.

$$(\tau\epsilon) = (\tau_0\epsilon_0) \quad \text{and} \quad T = T_0 \left(\frac{\tau_0}{\tau}\right)^{1/4}$$

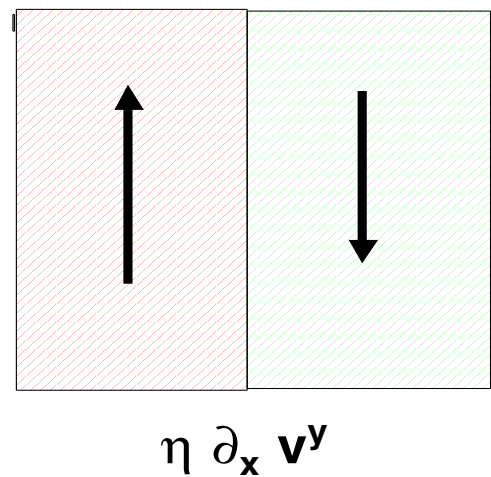
Temperature decrease slowly, $T \propto \left(\frac{1}{\tau}\right)^{1/3 \div 1/4}$

The particles per rapidity increases slowly, $\tau n \propto \tau^{0 \div 1/4}$

- η and σ appear in the combination $\frac{4}{3}\eta + \sigma$.



Transverse



- It is impossible to construct a flow which is damped only by the the bulk viscosity σ
- This makes it hard to measure σ .

How valid is Hydro? How much Entropy is produced?

$$\frac{d(\tau s)}{d\tau} = 0 \quad (\text{Ideal Case})$$

$$\frac{d(\tau s)}{d\tau} = \frac{\frac{4}{3}\eta + \sigma}{\tau T} \quad (\text{Viscous Case})$$

For hydrodynamics to be valid, the entropy produced over the time scale of the system, τ , must be small compared to the total :

$$\tau \frac{\frac{4}{3}\eta + \sigma}{\tau T} \frac{1}{\tau s} \equiv \Gamma_s \frac{1}{\tau} \ll 1$$

where $\Gamma_s \equiv \frac{\frac{4}{3}\eta + \sigma}{e+p}$ is the *Sound Attenuation Length*. Note ($sT = e + p$).

Estimates of Shear Viscosity:

$$\underbrace{T^{00} + T^{zz}}_{\text{indep. of Bag Const.}} = (e + p) + \eta \langle \partial^z v^z \rangle$$

$$\sim (e + p) \left[1 + \underbrace{\ell_{m.f.p.}}_{1/(n\sigma_0)} \langle \partial^z v^z \rangle \right]$$

Using $e + p \sim nT$, then find:

$$\Gamma_s \sim \ell_{m.f.p.} \quad \text{and} \quad \eta \sim (d.o.f.) \frac{T}{\sigma_0} \quad \text{and} \quad \frac{\Gamma_s}{\tau} \sim \frac{\ell_{m.f.p.}}{\tau} \ll 1$$

Estimates of η for the QGP and Heavy Ion Collisions

Perturbative QCD – Arnold, Moore, Yaffe.

- $\eta \approx 86 T^3 \frac{1}{g^4 \log(1/g)}$. Based upon kinetic theory of quarks and gluons.

Estimate: (d.o.f) = 36 and $\sigma_0 \sim \frac{g^4}{T^2} 4$ then $\eta \sim 36 \frac{T^3}{g^4}$.

Set $\alpha_s \rightarrow 1/2$ and $\log(1/g) \rightarrow 1$

$$\left(\frac{\Gamma_s}{\tau} \right) \approx 0.18 \frac{1}{\tau T} \quad (1)$$

- Leading order. $\eta \approx 150 T^3 \frac{1}{g^4}$ then

$$\left(\frac{\Gamma_s}{\tau} \right) \approx 0.4 \frac{1}{\tau T}$$

Strongly Coupled conformal N=4 SYM – Son, Starinets, Policastro

- No kinetic theory exists. Like most real liquids.

$$\left(\frac{\Gamma_s}{\tau} \right) = \frac{1}{3\pi} \frac{1}{\tau T} \approx 0.11 \frac{1}{\tau T} \quad (2)$$

Phenomenology – Molnar

Found could fit elliptic flow $v_2(p_T)$ only when

- $\frac{dN}{d\eta} = 1000$, $\sigma_0 = 10 \div 20$, and $\tau_o = 0.1$ fm.

$$\Gamma_s = 0.421 \frac{1}{n\sigma_0} \quad \left(\frac{\Gamma_s}{\tau} \right) = 0.02 \div 0.04 \quad (3)$$

- Constant cross section. Independent of time!

Best Guess: (At time τ_0)

$$T_0 \sim 250 \text{ MeV} \quad \tau_0 \sim 1 \text{ fm}$$

$$\left(\frac{\Gamma_s}{\tau} \right)_0 \approx 0.1 - 0.4$$

How does it evolve ???

Thermalization: How does Γ_s/τ evolve?

1. Bjorken Expansion | Scale Invariant Cross Section: $\sigma \sim \frac{\alpha_s^2}{T^2}$

- When Entropy is conserved: $T \sim \frac{1}{\tau^{1/3}}$

$$\frac{\Gamma_s}{\tau} \sim \frac{\#}{\tau T} \sim \# \frac{1}{\tau^{2/3}}$$

- When $\frac{dE}{dy}$ is conserved (entropy is produced): $T \sim \frac{1}{\tau^{1/4}}$

$$\frac{\Gamma_s}{\tau} \sim \frac{\#}{\tau T} \sim \# \frac{1}{\tau^{3/4}}$$

⇒ rapid to rapid++ thermalization

2. Bjorken Expansion | Constant Cross Section: $\sigma = \sigma_0$

- When Entropy is Conserved: $\tau n \sim \text{Const}$

$$\frac{\Gamma_s}{\tau} \sim \frac{\ell_{m.f.p.}}{\tau} \sim \frac{1}{\tau n \sigma_0} \sim \text{Const}$$

- When $\frac{dE}{dy}$ is conserved (entropy is produced): $\tau n \sim \tau^{1/4}$

$$\frac{\Gamma_s}{\tau} \sim \frac{\ell_{m.f.p.}}{\tau} \sim \frac{1}{\tau n \sigma_0} \sim \frac{1}{\tau^{1/4}}$$

⇒ Constant to slow thermalization

Spherical Expansion | Scale Invariant Cross Section: $\sigma \sim \frac{\alpha^2}{T^2}$

- Entropy conservation: $(sV) \sim \text{Const}$ and $s \sim T^3$. Then $T \sim \frac{1}{\tau}$.

$$\frac{\Gamma_s}{\tau} \sim \frac{\#}{\tau T} \sim \text{Const}$$

- Energy conservation: $(eV) \sim \text{Const}$ and $e \sim T^4$ $T \sim \frac{1}{\tau^{3/4}}$

\implies Constant to slow thermalization

Spherical Expansion | Constant Cross Section: σ_0

- Entropy Conservation: $(nV) \sim \text{Const}$. $n \sim \frac{1}{\tau^3}$

$$\frac{\Gamma_s}{\tau} \sim \frac{\ell_{m.f.p.}}{\tau} \sim \frac{1}{\tau n \sigma_0} \sim \frac{\tau^2}{\sigma_0}$$

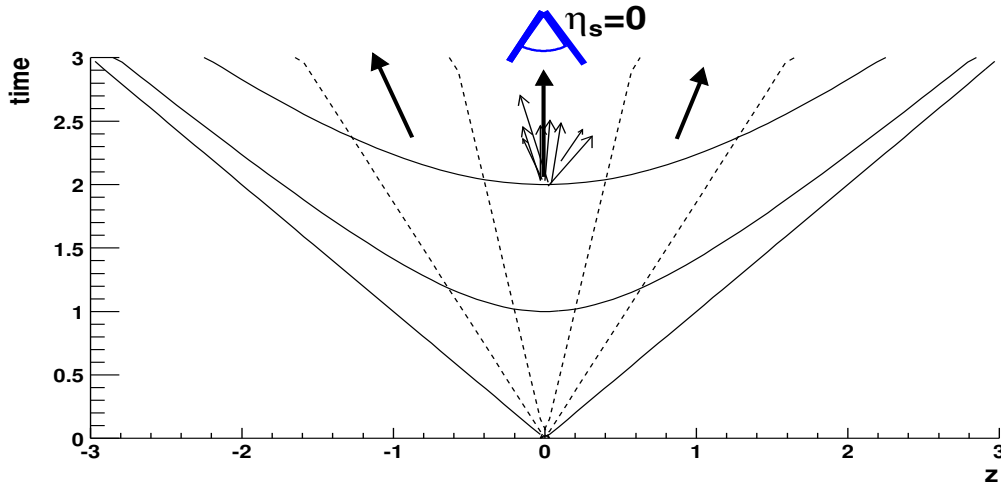
- Energy Conservation: $(eV) \sim \text{Const}$. and $n \sim T^3 \sim 1\tau^{9/4}$

$$\frac{\Gamma_s}{\tau} \sim \frac{\ell_{m.f.p.}}{\tau} \sim \frac{1}{\tau n \sigma_0} \sim \frac{\tau^{5/4}}{\sigma_0}$$

\implies rapid++ to rapid breakup.

- Non-equilibrium processes (entropy production) do not seem to dramatically change the course of thermalization.
- The introduction of mass scales is of essential importance to the question of thermalization in heavy ion collisions.
- The problem is three dimensional after a $\tau \sim R_A$.

Thermal smearing



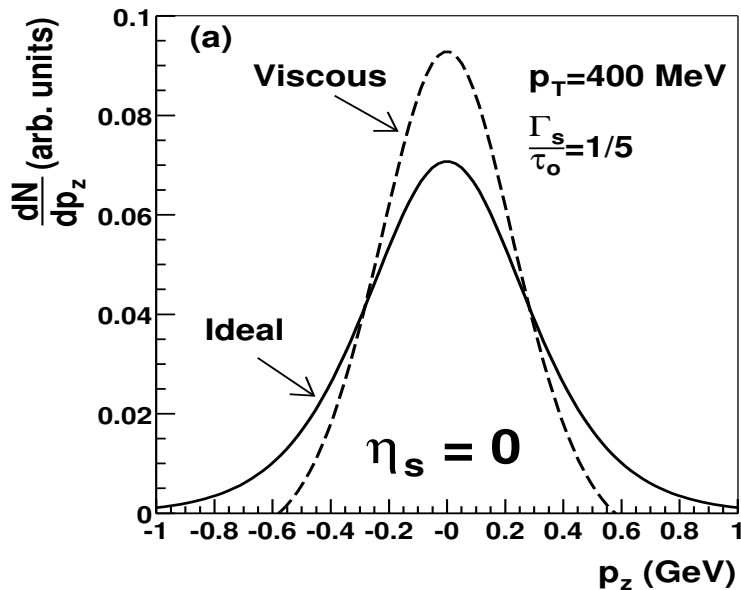
In equilibrium the thermal distribution is

$$f_0 = \frac{1}{e^{p_\alpha U^\alpha / T} - 1} = \frac{1}{e^{m_T \cosh(y - \eta_s)} - 1} \rightarrow \frac{1}{e^{E/T} - 1}$$

The effect of the viscosity is to reduce the longitudinal pressure.

$$T^{zz} = p - \frac{4}{3} \frac{\eta}{\tau} = \int d^3 p \frac{p^z a p^z}{E} (f_0 + \delta f)$$

The situation is the following:



Want to calculate δf : Use the linearized Boltzmann equation

$$\frac{p^\mu}{E} \partial_\mu f_p = \int_{1,2,3} d\Gamma_{12 \rightarrow 3p} (f_1 f_2 - f_3 f_p)$$

Linearize the Boltzmann equation:

- Substitute $f \rightarrow f^e + \delta f$ with $f_p^e = e^{-pu/T}$
- Keep first order in gradients.
- Use equilibrium: $f_1^e f_2^e = f_3^e f_4^e$

$$\frac{p^\mu}{E} \partial_\mu f_p^e = \int_{1,2,3} d\Gamma_{12 \rightarrow 3p} f_1^e f_2^e \left[\frac{\delta f_1}{f_1^e} + \frac{\delta f_2}{f_2^e} - \frac{\delta f_3}{f_3^e} - \frac{\delta f_4}{f_4^e} \right]$$

This is an integral equation for δf .

- δf is proportional to the strains:
 $\langle \nabla_\mu u_\nu \rangle, \nabla_\mu u^\mu, \nabla_\mu T$.
- δf is a scalar $\delta f \propto \chi(p) p^\mu p^\nu \langle \partial_\mu u_\nu \rangle$.
- If I restrict $f(p) = f_o(1 + g(p))$ where $g(p)$ is a polynomial of degree less than two. Then the form is completely determined:

$$f = f_o \left(\frac{p \cdot u}{T} \right) \left(1 + \frac{C}{T^3} p_\mu p_\nu \frac{\langle \partial^\mu u^\nu \rangle}{2} \right)$$

- This is sometimes called the first approximation

Refined analysis.

$$\frac{p^\mu}{E} \partial_\mu f_p^e = \int_{1,2,3} d\Gamma_{12 \rightarrow 3p} f_1^e f_2^e \left[\frac{\delta f_1}{f_1^e} + \frac{\delta f_2}{f_2^e} - \frac{\delta f_3}{f_3^e} - \frac{\delta f_4}{f_4^e} \right]$$

Which gradients actually appear? $\partial_\mu = -u_\mu D + \nabla_\mu$

$$p^\mu \partial_\mu (e^{-pu/T}) = -f^e \left[\underbrace{-(p \cdot u) \left(\frac{p}{T} \cdot Du \right) - (p \cdot u)^2 D \left(\frac{1}{T} \right)}_{\substack{\frac{p^\mu p^\alpha}{T} \nabla_\mu u_\nu + (p \cdot u) (p \cdot \nabla \left(\frac{1}{T} \right))}} \right] +$$

- Use ideal EOM $Du = -\frac{\nabla p}{e+p}$ then find

$$\underbrace{\dots}_{\substack{\frac{p^\mu p^\alpha}{T} \nabla_\mu u_\nu + (p \cdot u) (p \cdot \nabla \left(\frac{1}{T} \right))}} \propto \frac{1}{T} \frac{\nabla p}{e+p} + \nabla \left(\frac{1}{T} \right) = \frac{n}{e+p} \nabla(\mu/T) = 0$$

- $D(1/T) \propto De$. Then use ideal EOM $De = -(e+p) \nabla_\mu u^\mu$

Put it all together:

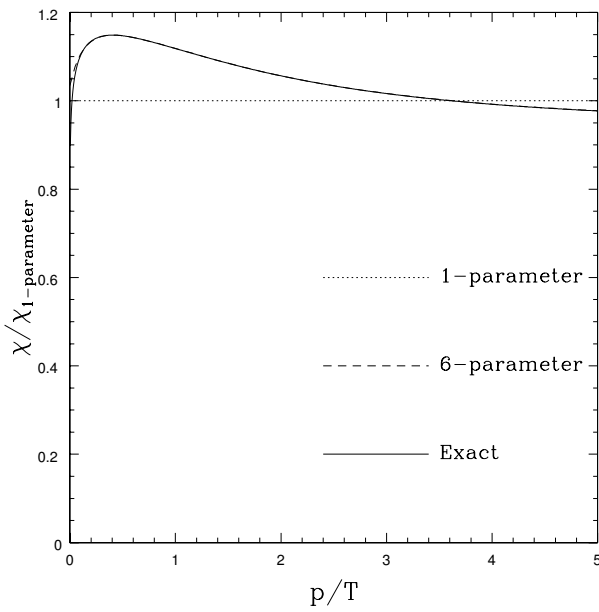
$$p^\mu \partial_\mu f^e = -f^e \left[\underbrace{\left(-\frac{(p \cdot u)^2}{T} \frac{e+p}{T c_v} + \frac{1}{3} \frac{p \cdot \Delta \cdot p}{T} \right)}_{\text{viscous correction}} \nabla_\mu u^\mu + \frac{p^\mu p^\alpha}{T} \langle \nabla_\mu u_\alpha \rangle \right] = C[\delta f]$$

- The form of the viscous correction is not determined by symmetry alone.
 - $\nabla \left(\frac{1}{T} \right)$ Gets converted to $\nabla \left(\frac{\mu}{T} \right)$ using the ideal e.o.m. and the properties of the equilibrium distribution.
 - Microscopic manifestation of the Onsager relation.
- Look at the **Bulk** viscosity. For a massless ideal gas we have: $\epsilon \propto T^4$ and $T c_v = 4e$ and $e + p = \frac{4}{3}e$.

$$\underbrace{\dots}_{\text{bulk viscosity}} = 0$$

- The bulk viscosity vanishes for a scale invariant ultra-relativistic gas. (Also vanishes for a non-relativistic Boltzmann gas)
- The form of the **Shear** Correction motivates the polynomial ansatz taken in the previous slide.

$$\delta f \propto f^e \frac{p_\mu p_\nu}{T} \langle \partial^\mu u^\nu \rangle$$



$$f = f_o\left(\frac{p \cdot u}{T}\right) \left(1 + \frac{C}{T^3} p_\mu p_\nu \frac{\langle \partial^\mu u^\nu \rangle}{2}\right)$$

The constant $\frac{C}{T}$ is essentially the sound attenuation constant:

$$T^{\mu\nu} = \int d^3p \frac{p^\mu p^\nu}{E} f$$

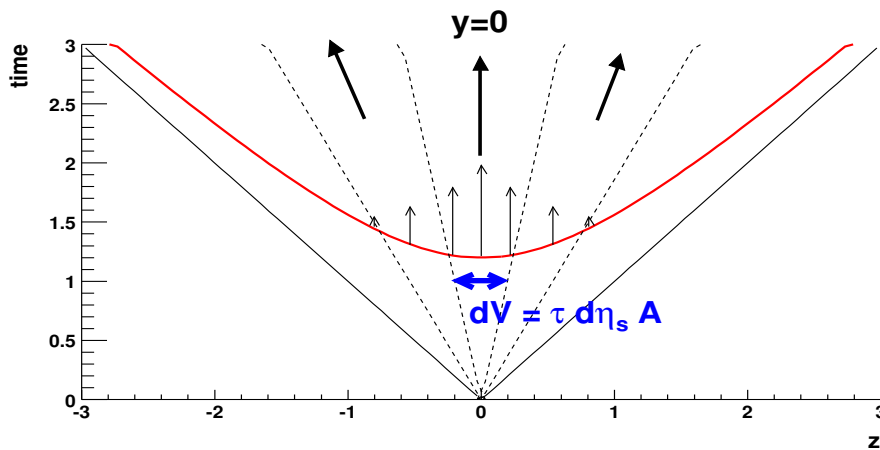
$$T_o^{\mu\nu} + T_{vis}^{\mu\nu} = \int d^3p \frac{p^\mu p^\nu}{E} (f_o + \delta f)$$

Then looking only at the viscous piece:

$$T_{vis}^{\mu\nu} = \eta \langle \partial^\mu u^\nu \rangle = \underbrace{\int d^3p \frac{p^\mu p^\nu}{E} f_o}_{\text{viscous}} \frac{C}{T^3} p_\alpha p_\beta \frac{\langle \nabla_\alpha u_\beta \rangle}{2}$$

- Classical Gas: $C = \frac{\eta}{s}$
- Massless Bose Gas: $C = 0.96 \frac{\eta}{s}$
- $\frac{3C}{4T} \approx \Gamma_s$

Thermal Transverse Momentum Spectra at Mid rapidity:

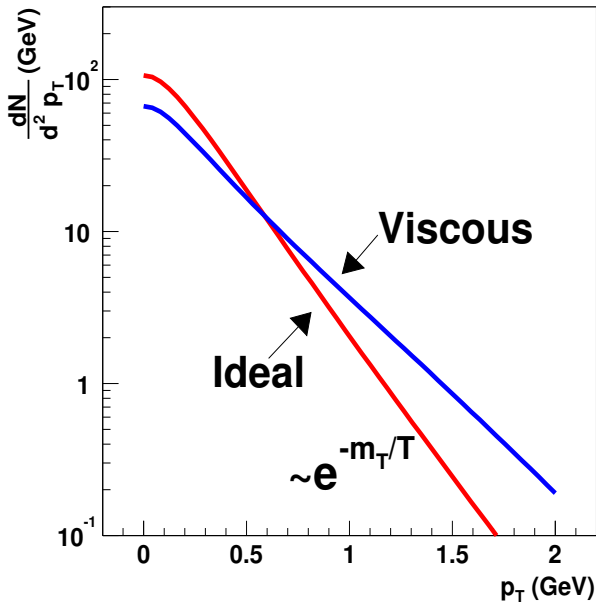


$$E \frac{d^3 N}{d^3 p} = \frac{d^2 N}{d^2 p_T dy} = \int \underbrace{p^\mu d\Sigma_\mu}_{E dV} f$$

Lets compute this integral:

$$\begin{aligned} \frac{dN}{d^2 p_T dy} &= \int dV m_T \cosh(\eta_s) e^{-p u/T} \\ &= \int A \tau d\eta_s m_T \cosh(\eta_s) e^{-\frac{m_T}{T} \cosh(\eta_s)} \\ &= (A \tau) m_T 2 K_1 \left(\frac{m_T}{T} \right) \end{aligned}$$

Viscous corrections to p_T spectrum: Qualitative



The transverse pressure is larger with viscosity:

$$T_{zz} = p - \frac{4}{3} \frac{\eta}{\tau}$$

$$T_{xx} = T_{yy} = p + \frac{2}{3} \frac{\eta}{\tau}$$

Viscous corrections to p_T spectrum: Quantitative

$$dN_o + \delta dN = \int p^\mu d\Sigma_\mu f_o + \delta f$$

Want to compute $\frac{\delta dN}{dN_o}$:

$$\delta f = f_o \Gamma_s \frac{p_\alpha p_\beta}{T} \Gamma_s \langle \nabla^\alpha u^\beta \rangle \sim f_o \left(\frac{p_T}{T} \right)^2 \frac{2}{3} \frac{\Gamma_s}{\tau}$$

Now you can do these integrals:

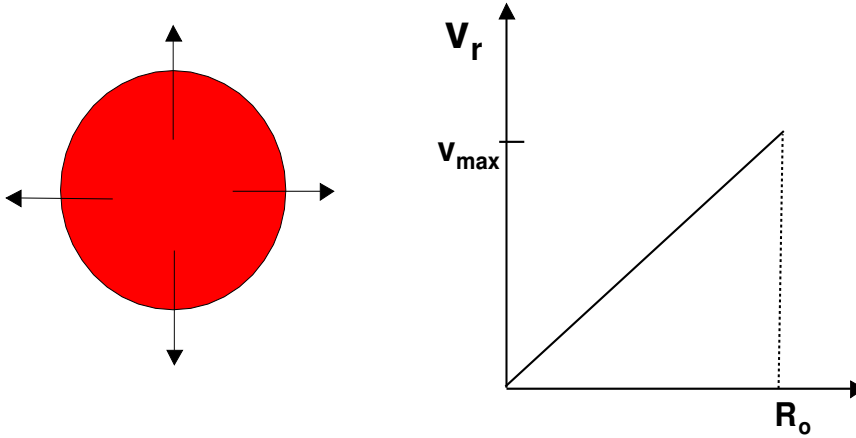
$$\frac{\delta dN}{dN_o} = \frac{\Gamma_s}{4\tau} \left\{ \left(\frac{p_T}{T} \right)^2 - \left(\frac{m_T}{T} \right)^2 \frac{1}{2} \left(\frac{K_3\left(\frac{m_T}{T}\right)}{K_1\left(\frac{m_T}{T}\right)} - 1 \right) \right\}$$

$$\rightarrow \frac{\Gamma_s}{4\tau} \left(\frac{p_T}{T} \right)^2$$

$$\frac{\delta dN}{dN_o} = \frac{\Gamma_s}{4\tau} \left(\frac{p_T}{T} \right)^2$$

- Viscous corrections grow with transverse momentum.
- When viscous corrections become of order one, then we are supposed to throw away hydrodynamics.
- Viscosity puts a bound on how high in p_T the hydrodynamics may be applied.
- For this room: $\Gamma_s/\tau \approx 10^4$ and $p_T^{max}/T = \sqrt{\frac{\tau}{\Gamma_s}} \approx 10^2$.
 $n \sim e^{-p/T}$ so you can forget about it.
- For heavy ion collisions: $T \approx 200 \text{ MeV}$ find
 $p_T^{max} \approx 500 \text{ MeV}$. (Actually it is closer to 1.5 GeV)

Spectra with transverse expansion :



Compute $\langle \partial^\mu u^\nu \rangle$:

- Now Find two gradients: $\frac{1}{\tau}$ and $\frac{v_{max}}{R_o}$
- Compute the correction to the spectrum. Each term in $p_\mu p_\nu \langle \partial^\mu u^\nu \rangle$ gives a couple of Bessels.
- For large p_T

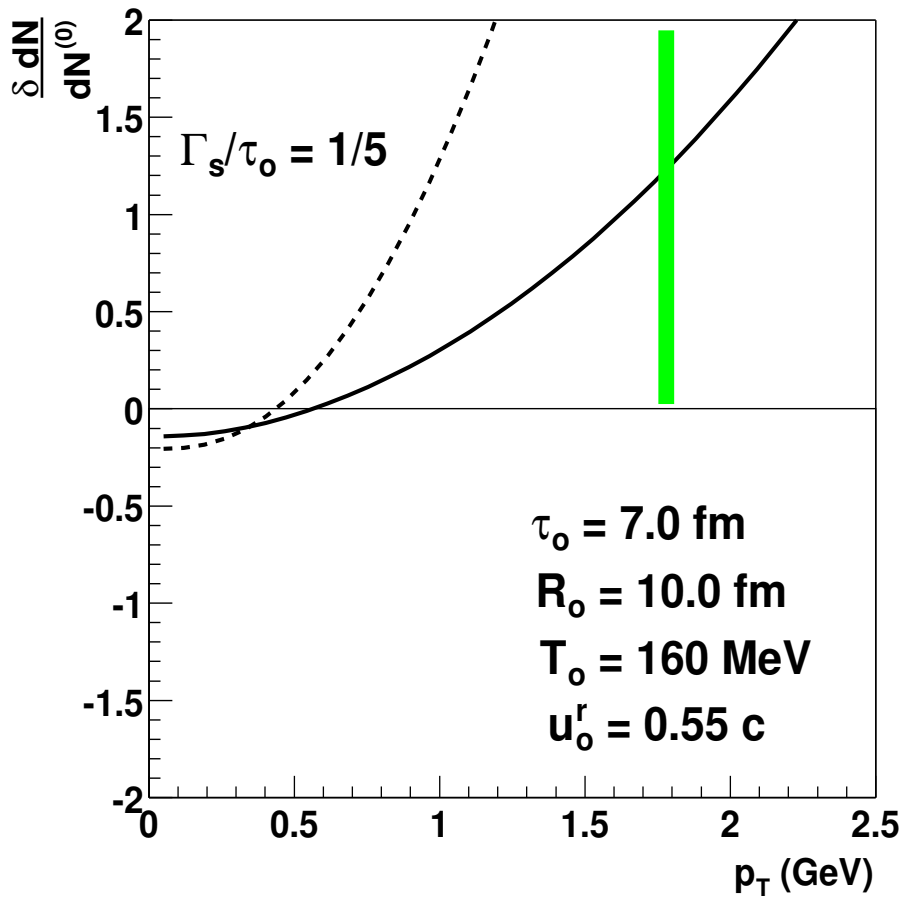
$$\frac{\delta dN}{dN_o} = \frac{\Gamma_s}{4\tau} \left(\frac{p_T}{T_{eff}} \right)^2 \left(\frac{1}{\tau} - \frac{v_{max}}{R} \right)$$

where

$$T_{eff} = T \sqrt{\frac{1+v}{1-v}}$$

Two Mitigating Factors:

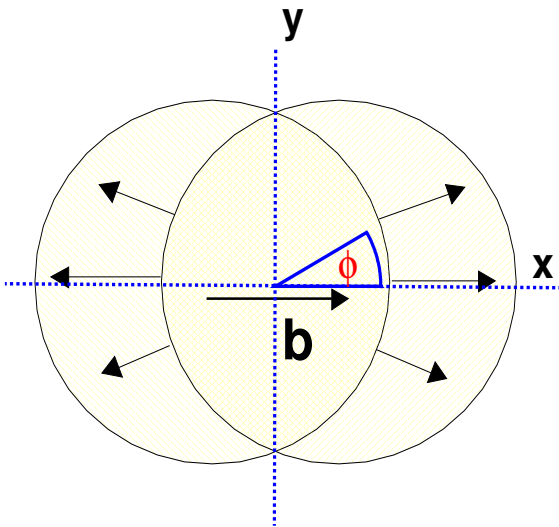
- The particles are blue shifted out to higher p_T
- The transverse flow alleviates the longitudinal shear.



$$\frac{\delta dN}{dN^{(0)}} \equiv \frac{\frac{dN^{(1)}}{p_T dp_T dy}}{\frac{dN^{(0)}}{p_T dp_T dy}}$$

The maximum possible p_T accessible to Hydrodynamics is ~ 1.8 GeV – A couple of times T_{eff} .

Elliptic Flow in Heavy Ion Collisions: Qualitative

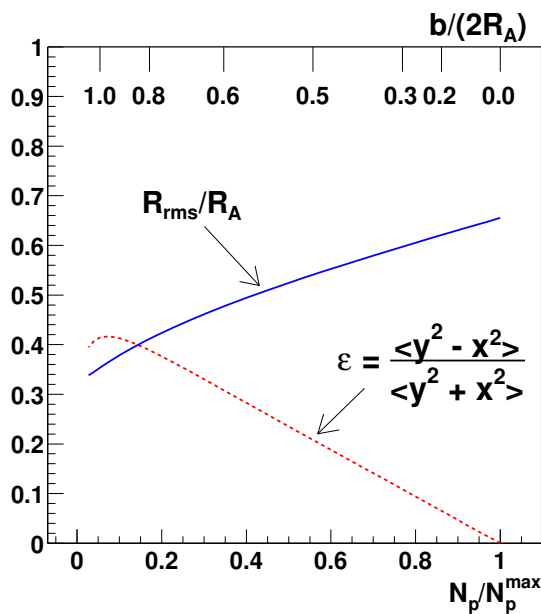


Measure the Anisotropy:

$$\frac{dN}{d\phi} = N(1 + 2v_2 \cos(2\phi) + \dots)$$

where $v_2 = \langle \cos(2\phi) \rangle$

Categorize the collision geometry:



1. $N_p \equiv$ The number of participants

participating nucleons.

2. $R_{rms} \equiv \sqrt{\langle x^2 + y^2 \rangle}$.

The size of the collision zone.

3. $\epsilon \equiv$ The anisotropy of the initial geometry

Facts:

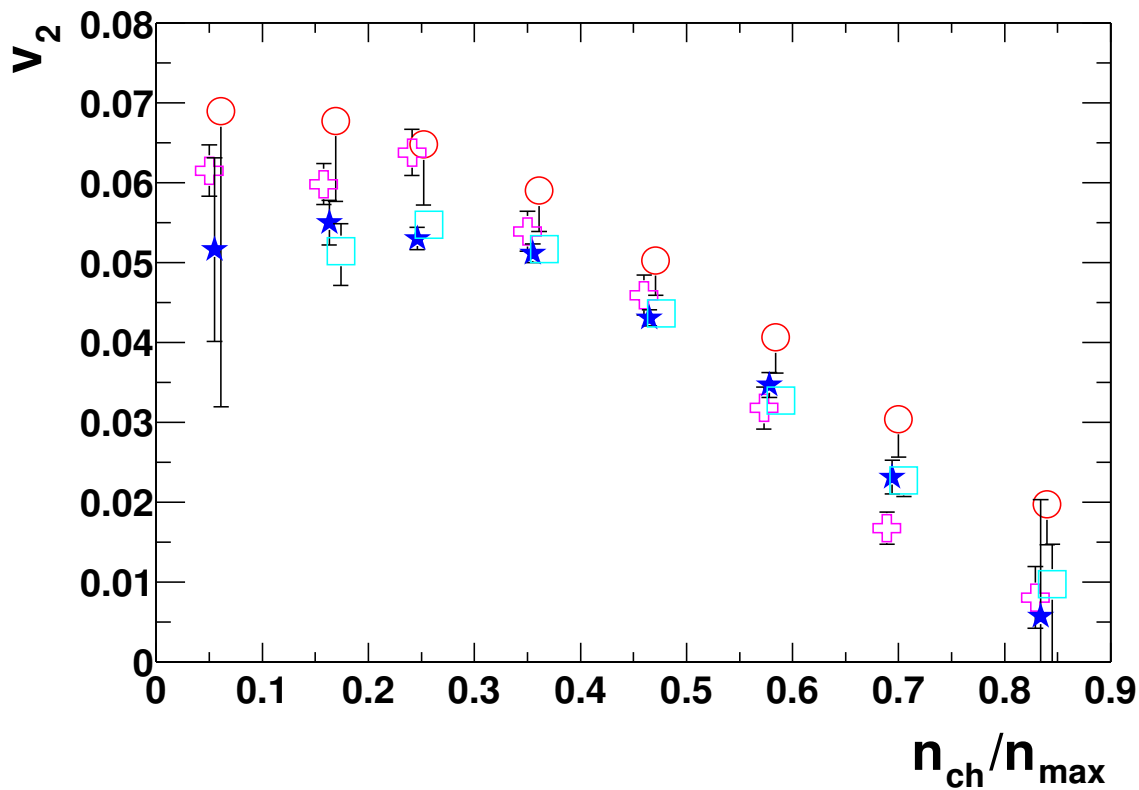
1. $\frac{dN}{dy} \propto N_p =$ the number of participants

2. $\epsilon \propto N_p =$ the number of participants nucleons.

3. Centrality $\approx \left(\frac{b}{2R_A}\right)^2$. Example 16 – 24% central is $b \approx 7 \text{ fm}$

Observation of v_2 at RHIC!

Look at stars!



- If nothing changes as a function of centrality then expect:
 $v_2 \propto \epsilon$
- Up to corrections: , $v_2 \propto \epsilon$ in data

Also measure v_2 as a function of transverse momentum,

$$\frac{1}{p_T} \frac{dN}{dp_T d\phi} = \frac{1}{p_T} \frac{dN}{dp_T} (1 + 2 v_2(p_T) \cos(2\phi) \dots)$$

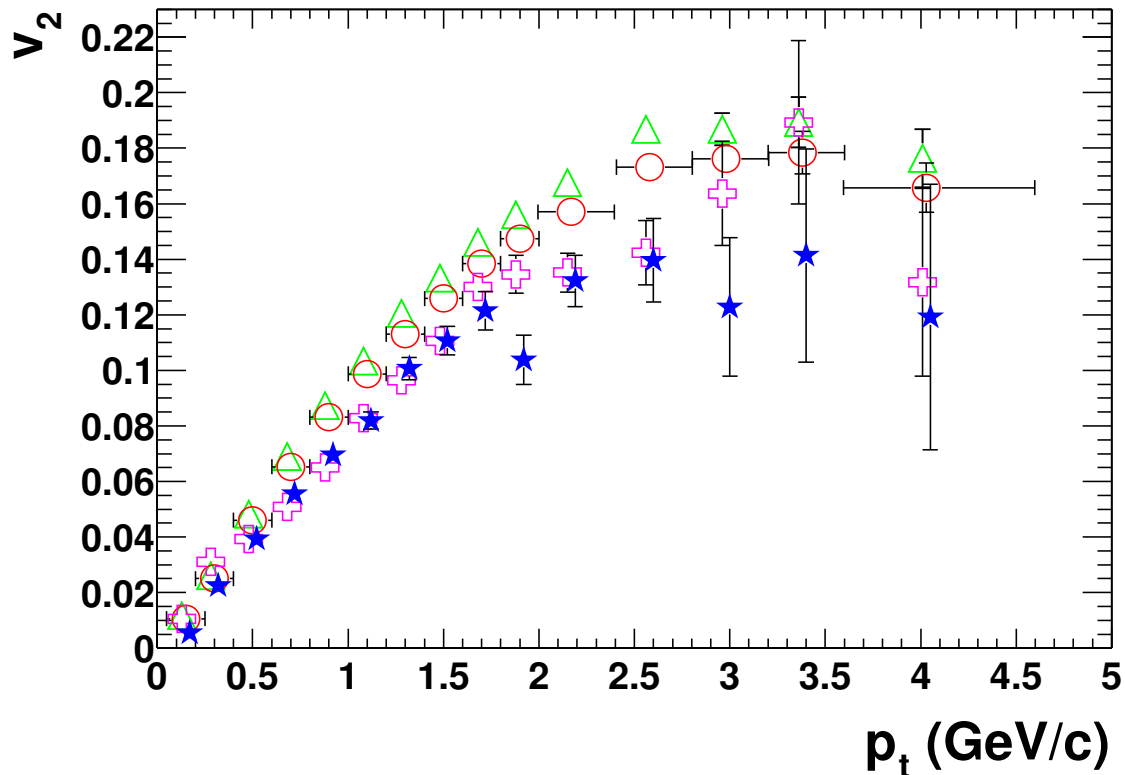
Then $v_2(p_T) \equiv \langle \cos(2\phi) \rangle_{p_T}$.

It seems:

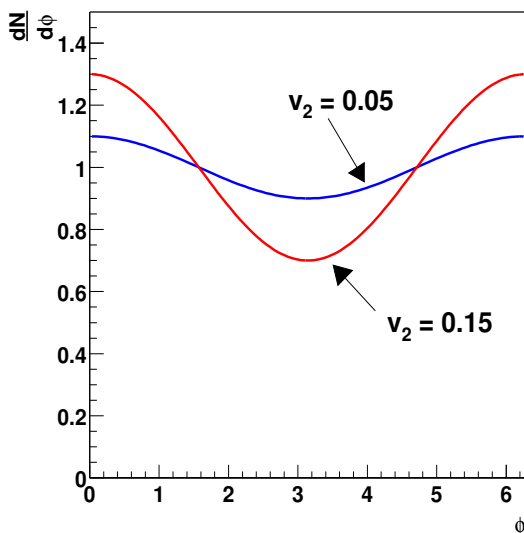
V_2 breaks down like a

Viscous Fluid

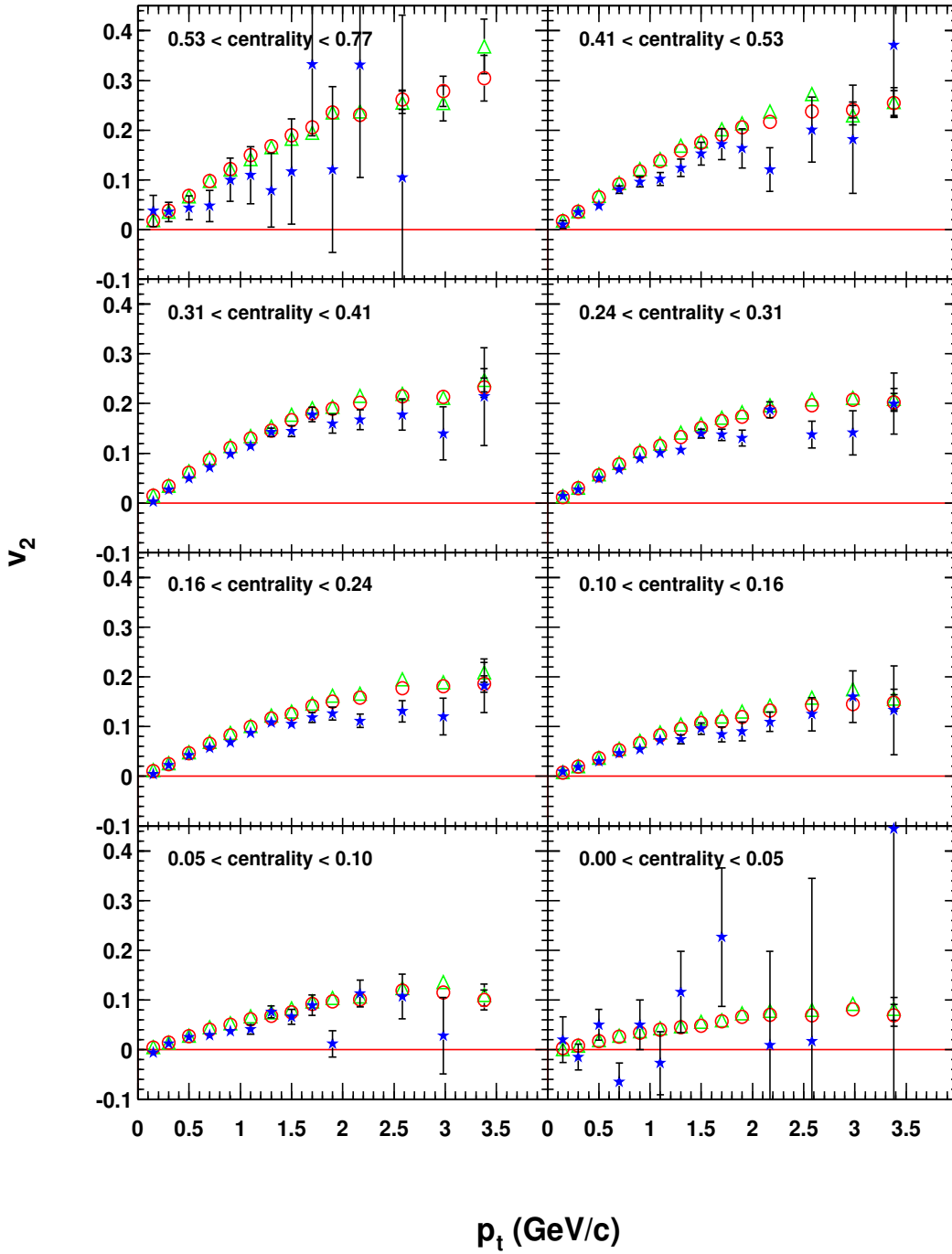
$b \approx 6 \text{ fm}$



- $v_2(p_T)$ increases as a function p_T until $p_T \approx 2.0 \text{ GeV}$ and then flattens at $v_2 \approx 0.15$
- v_2 is large even at $p_T \approx 4.0 \text{ GeV}$. There is a 1.8 to 1 asymmetry between x and y at $p_T = 3.0 \text{ GeV}$.



Flow as function of centrality and p_T .



Basic Analysis of Elliptic Flow:

- Since ϵ is small we expect:

$$v_2 \propto \epsilon \propto 1 - N_p/N_p^{max}$$

- For a system with no other scales in the problem, the physics is independent of centrality. Expect

$$v_2 = \text{Cons}(1 - N_p/N_p^{max})$$

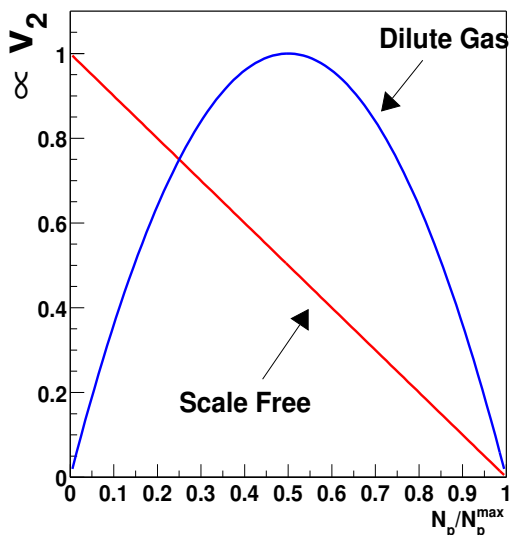
Ideal hydrodynamics has no scales and the response is essentially trivially related to geometry.

- For a **dilute system** (with constant cross sections) we expect collective response to be proportional to multiplicity

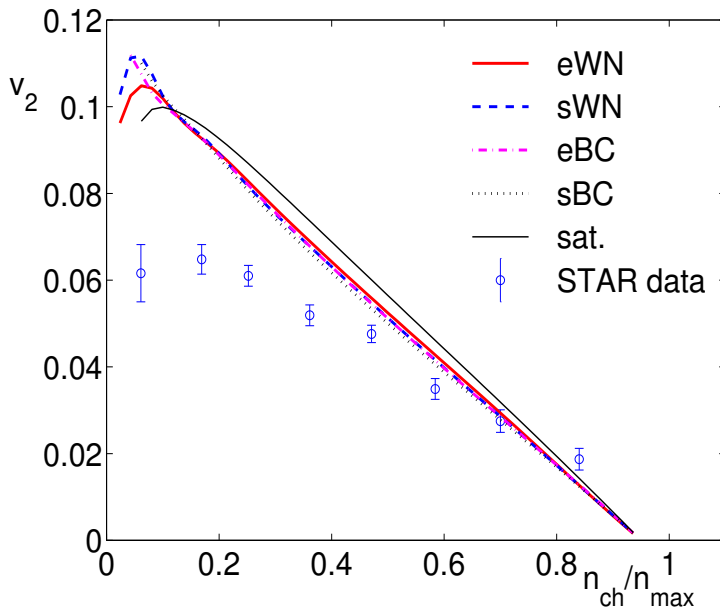
$$v_2 \propto \frac{dN}{dy} \propto N_p.$$

$$v_2 \propto N_p(1 - N_p/N_p^{max})$$

- **Viscous hydrodynamics** is in-between these two cases.

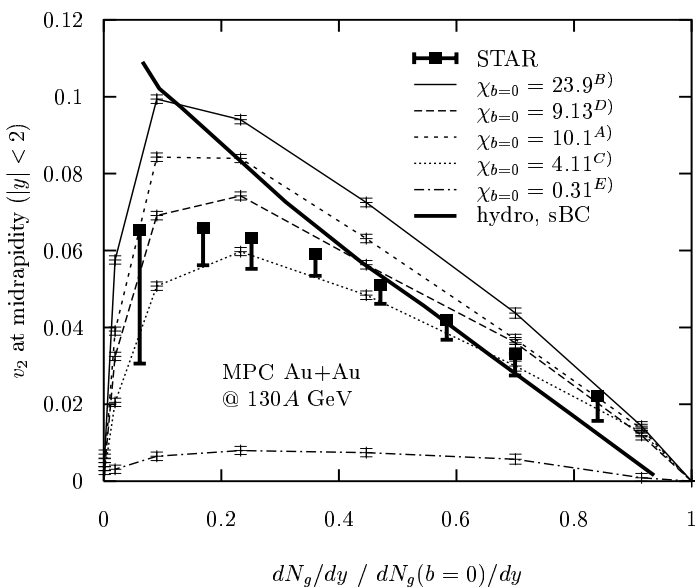


Ideal Hydrodynamics: (Peter Kolb and U. Heinz)



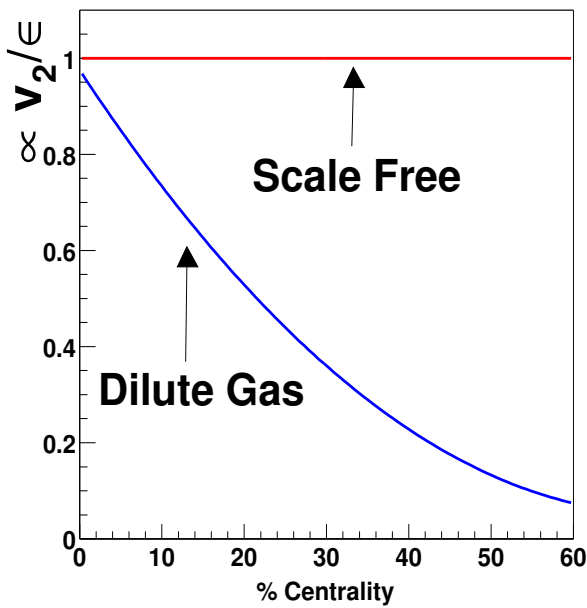
The solution is directly proportional to ϵ . There is no scale.

Solution to Boltzmann Equation: (Denes Molnar and M. Gyulassy)

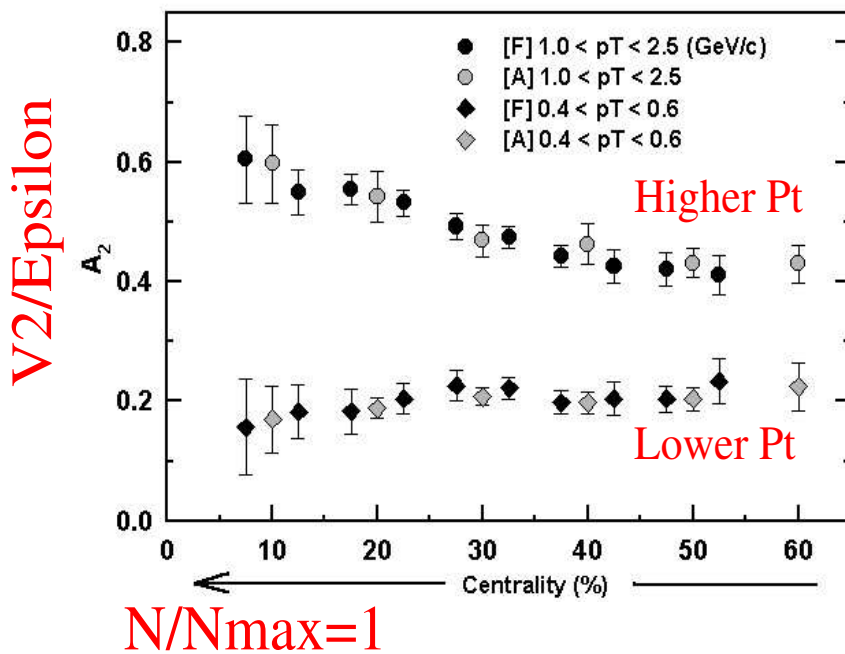


- $\chi_{b=0} = 10$ corresponds to $(\Gamma_s/\tau)_0 \approx 0.04$
- For the Boltzmann equation, v_2 curves over in peripheral collisions.

Translation: Centrality $\approx (b/2R_A)^2$



Now let us look more differentially.

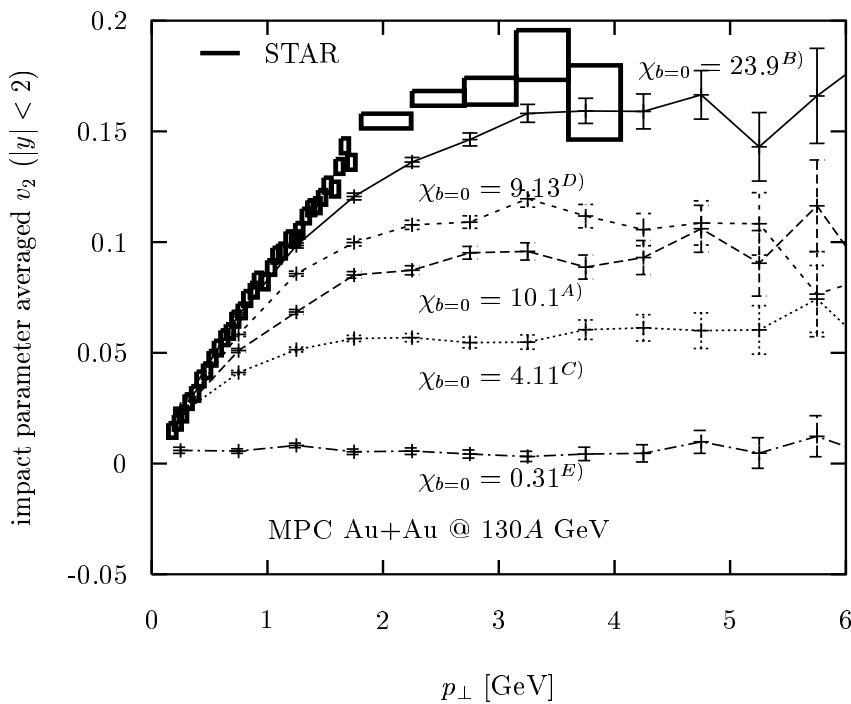


- At **Lower Pt** ≈ 0.6 GeV the response is directly proportional to ϵ
- At **Higher Pt** ≈ 1.4 GeV the effects of other scales come in.

This is naturally understood as a viscous effect.

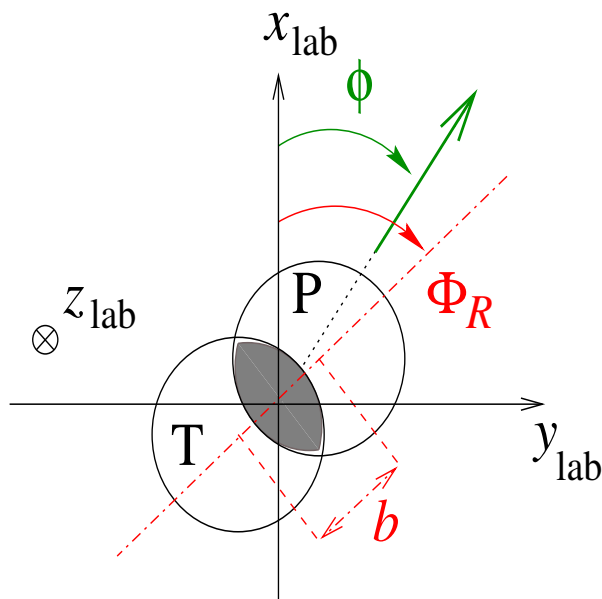
Solution of the Boltzmann Equation: Denes Molnar + M. Gyulassy

● Classical Massless Particles with Constant Cross Sections



- The Boltzmann equation **predicted** a flattening of v_2 at high p_T .
- $\chi_{b=0} \approx 10$ corresponds to $(\Gamma_s/\tau)_0 = 0.04$
- The observed v_2 **breaks down** in a way consistently with viscous/Boltzmann effects.
- Need **analytic** understanding. Some understanding from viscous correction to the thermal distribution function.

Determination of Elliptic Flow: (N. Borghini and J.Y. Ollitrault)



How to determine Φ_R ?

- Two particles widely separated in phase space are not generally correlated.
- If there is flow then all particles are correlated with the reaction plane.
- Extract v_2 from inter-particle correlations.

Define: $\langle \rangle \equiv$ The average over all events

- The definition of v_2 is

$$\langle e^{2i(\phi - \Phi_R)} \rangle \equiv v_2$$

- The reaction plane is random

$$\langle e^{2i\Phi_R} \rangle = 0$$

Look at the two particle irreducible correlation and assume no correlations except with the reaction plane:

$$\begin{aligned}\langle e^{2i(\phi_1 - \phi_2)} \rangle &= \langle e^{2i(\phi_1 - \Phi_R) - 2i(\phi_2 - \Phi_R)} \rangle \\ &= \langle e^{2i(\phi_1 - \Phi_R)} \rangle \langle e^{2i(\phi_2 - \Phi_R)} \rangle + O(1/M_{part}) \\ &= v_2^2 + O(1/M)\end{aligned}$$

- The error is $\delta v_2 \propto O(1/\sqrt{M})$:

Now look at the four particle irreducible correlation:

$$\begin{aligned}c_4 &\equiv \langle e^{2i(\phi_1 + \phi_2 - \phi_3 - \phi_4)} \rangle \\ &\quad - \langle e^{2i(\phi_1 - \phi_3)} \rangle \langle e^{2i(\phi_2 - \phi_4)} \rangle - \langle e^{2i(\phi_1 - \phi_4)} \rangle \langle e^{2i(\phi_2 - \phi_3)} \rangle\end{aligned}$$

If we assume that there is no correlation except with the reaction plane we have:

$$c_4 = v_2^4 - 2v_2^4 + O(1/M^3) = -v_2^4 + O(1/M^3)$$

- The error is $\delta v_2 \propto O(1/M^{3/4})$.
- Flow like correlations do not decrease as we look at higher multiparticle correlation functions: $(|c_n|)^{1/n} = v_2$
- The contributions of long range correlations goes from $1/\sqrt{M}$ to $1/M$ as we go to higher and higher cummulants:
 $(\text{Non-Flow}_n)^{1/n} = O(1/M^{1-1/n})$

Relation to Yang-Lee Zeros: (R.S. Bahler, N. Borgini,
J.Y. Ollitrault)

Is there a way to extract the limit: $\lim_{n \rightarrow \infty} (|c_n|)^{1/n} = v_2$?

The Advection Diffusion Equation:

Ideal Advection: Moving Along With the Stream

$$N^\mu = nu^\mu$$

Viscous Diffusion:

$$N^\mu = nu^\mu + J_D^\mu$$

For Navier Stokes:

$$J_D^\mu = \lambda(g^{\mu\nu} + u^\mu u^\nu)\partial_\nu n$$

In the rest frame of the fluid the conservation law becomes the ordinary diffusion equation:

$$\partial_\mu N^\mu = 0 \quad \rightarrow \quad \begin{cases} \partial_t n + \partial_x j = 0 \\ j = -\lambda \partial_x n \end{cases}$$

Problems:

- Two time derivatives make the initial value problem ill defined.
- Infinite propagation speeds for parabolic differential equations.
- A linear stability analysis shows that the small perturbations grow exponentially.
- Gets worse for Navier-Stokes equations.

The Relaxation Time Approximation:

In the rest frame, it takes a time τ_R for the current to relax. Make j a dynamic variable.

$$\begin{aligned}\partial_t n + \partial_x j &= 0 \\ \partial_t j &= -\frac{(j + \lambda \partial_x n)}{\tau_R}\end{aligned}$$

For an Arbitrary Frame:

$$\begin{aligned}\partial_\mu N^\mu &= 0 \\ DJ_D^\mu &= -\frac{(J_D^\mu + \lambda \nabla^\mu n)}{\tau_R}\end{aligned}$$

where

$$\begin{aligned}N^\mu &= nu^\mu + J_D^\mu \\ DJ_D^\mu &= u^\alpha \partial_\alpha J^\mu \\ \nabla^\mu &= (g^{\mu\nu} + u^\mu u^\nu) \partial_\nu\end{aligned}$$

Questions:

- What is the relation of the relaxation time to the microscopic correlation function.
- Is this theory causal.
- Can I solve this system.

- Long time physics should be insensitive to short timescales in the problem.

Basics of Diffusion

A particle undergoing a random walk with velocity v_{th} and collision time τ_c .

$$\Delta L^2 \sim (v_{th}\tau_c)^2 \frac{T_{\text{diff}}}{\tau_c}$$

The mean width of a diffusing Gaussian grows:

$$\Delta L^2(t) = 2\lambda(T_{\text{diff}})$$

Therefore we have

$$\lambda \sim v_{th}^2 \tau_c \sim v_{th} \ell_{\text{mfp}}$$

Or

$$\frac{\lambda}{\tau_c} \sim v_{th}^2 \quad \text{and} \quad \frac{\lambda}{L} \sim v_{th} \frac{\ell_{\text{mfp}}}{L} \ll 1$$

For a Gaussian of length L with velocity $v \sim v_{th}$, a typical **Advection** time scale is:

$$T_{\text{adv}} \sim L/v_{\text{fluid}}$$

The **Diffusion** timescale is:

$$T_{\text{diff}} \sim L^2/\lambda$$

Therefore:

$$T_{\text{adv}} \ll T_{\text{diff}}$$

Relation to the correlation function:

From L. Kadanoff and P.C. Martin, Ann. Phys. 1965.

Then assume a small deviation from equilibrium n follows the same EOM.

$$\partial_t n(x, t) = \lambda \partial_x^2 n(x, t)$$

With the definitions

$$\langle n(t)n(0) \rangle_k \equiv \int dk e^{-ikx} \langle n(x, t)n(0, 0) \rangle$$

we have

$$\partial_t \langle n(t)n(0) \rangle_k = -\lambda k^2 \langle n(t)n(0) \rangle_k$$

Then introduce the one sided Fourier transform in time.

$$(nn)_{kw}^+ \equiv \int_0^\infty e^{i\omega t} \langle n(t)n(0) \rangle_k$$

This is related to the correlator by:

$$(nn)_{kw} \equiv \int_{-\infty}^\infty e^{i\omega t} \langle n(t)n(0) \rangle_k = 2\text{Re}(nn)_{kw}^+$$

Then (one-sided) Fourier transforming the EOM we find:

$$(nn)_{kw} = \frac{2\lambda k^2}{\omega^2 + (\lambda k^2)^2} \langle n(0)n(0) \rangle_k$$

Using the fluctuation dissipation theorem:

$$(nn)_{kw} = 2T \frac{\text{Im } \alpha(k, w)}{w}$$

Where

$$\alpha(k, w) = (i\theta(t)[n(t), n(0)])_{kw}$$

Thus we obtain:

$$\frac{\text{Im } \alpha(k, w)}{w} = \frac{2\lambda k^2}{w^2 + (\lambda k^2)^2} \frac{\langle n(0)n(0) \rangle_k}{T} \quad (4)$$

By taking limits we obtain the Kubo formula.

$$\frac{\langle n^2 \rangle}{T} \lambda = \lim_{w \rightarrow 0} \lim_{k \rightarrow 0} \frac{w}{k^2} \text{Im } \alpha(k, w) \quad (5)$$

λ is only determined by the Long time behavior of the correlation function

Werner-Israel Type Equation:

$$\begin{aligned}\partial_t n + \partial_x j &= 0 \\ \partial_t j &= -(j + \lambda \partial_x n) / \tau\end{aligned}$$

Combining equations we find:

$$\begin{aligned}\partial_t^2 n + \frac{\partial_t n}{\tau} + \frac{\lambda}{\tau} \partial_x^2 n &= 0 \\ \text{Initial Conditions} &= \begin{cases} n = n(0) \\ \partial_t n = 0 \end{cases}\end{aligned}$$

As before introduce the one sided Fourier transform and solve for $(nn)_{kw}^+$. We find

$$\frac{\text{Im } \alpha(k, \omega)}{\omega} = \frac{2 \lambda k^2}{\omega^2 + \tau^2 (\omega^2 - \frac{\lambda}{\tau} k^2)^2} \frac{\langle n(0)n(0) \rangle_k}{T}$$

- The correlator is the same, as before for small frequencies
- At high frequencies the correlator is different.

The Werner-Israel Equation at short times

$$\partial_t^2 n + \frac{\partial_t n}{\tau} + \frac{\lambda}{\tau} \partial_x^2 n = 0$$

$$\text{Initial Conditions} = \begin{cases} n = n(0) \\ \partial_t n = 0 \end{cases}$$

At short times the correlator (after spatial Fourier transforming)

$$\partial_t^2 \langle n(t)n(0) \rangle_k \Big|_{t=0} - \left[\frac{\lambda}{\tau} \right] k^2 \langle n(0)n(0) \rangle_k = 0$$

- The short time behavior is determined by the combination $\frac{\lambda}{\tau}$
- $\frac{\lambda}{\tau}$ is of order a typical thermal velocity squared v_{th}^2

An expression for the quantity $\frac{\lambda}{\tau}$ is after using the **Fluctuation Dissipation Theorem**:

$$2T \frac{\text{Im}\alpha(k, \omega)}{\omega} = (nn)_{k\omega}$$

We find

$$\lim_{k \rightarrow 0} \int \frac{d\omega}{2\pi} \omega^2 2T \frac{\text{Im}\alpha(k, \omega)}{\omega} = k^2 \left[\frac{\lambda}{\tau} \right] \langle n^2 \rangle$$

There is a sum rule relating this moment to the time derivative of the correlator at the origin.

The Riemann-Characteristic Problem

Write the equations of motion in the following form:

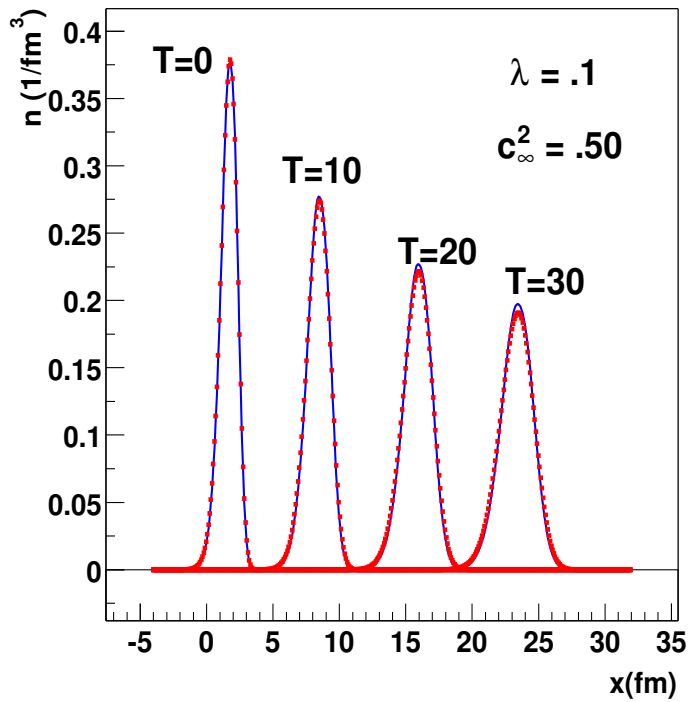
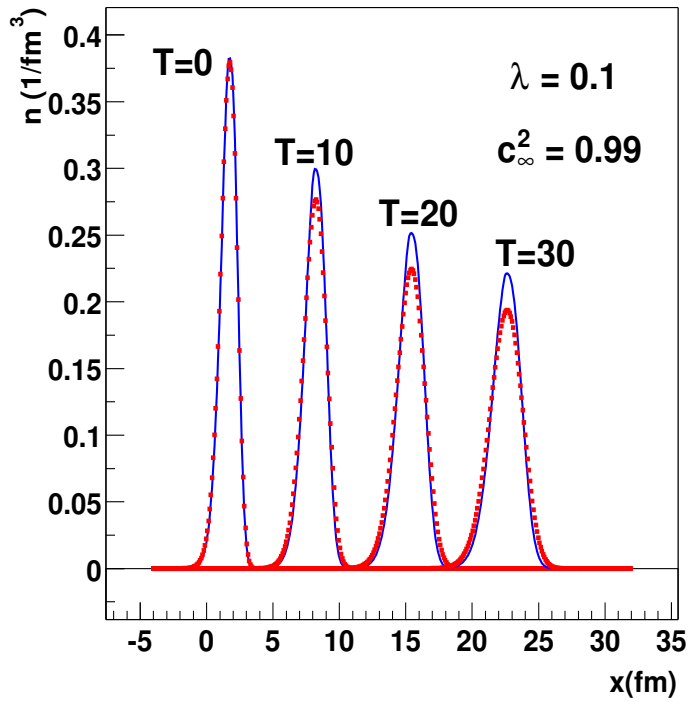
$$\begin{pmatrix} \mathbf{B} \end{pmatrix} \begin{pmatrix} \partial_t n \\ \partial_t j \end{pmatrix} + \begin{pmatrix} \mathbf{A} \end{pmatrix} \begin{pmatrix} \partial_x n \\ \partial_x j \end{pmatrix} = \begin{pmatrix} 0 \\ -j/\tau \end{pmatrix}$$

The **eigen values/vectors** of $\mathbf{B}^{-1}\mathbf{A}$ are the **signal velocities** of the equation of motion.

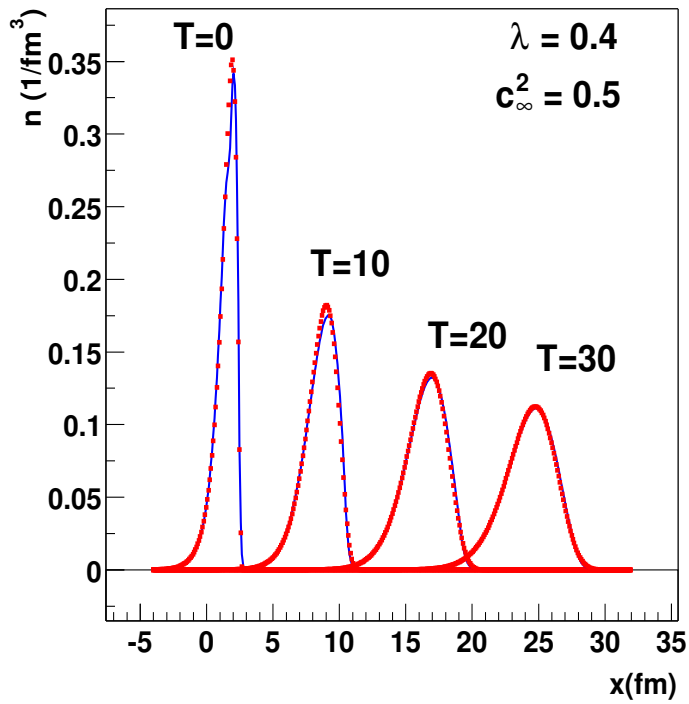
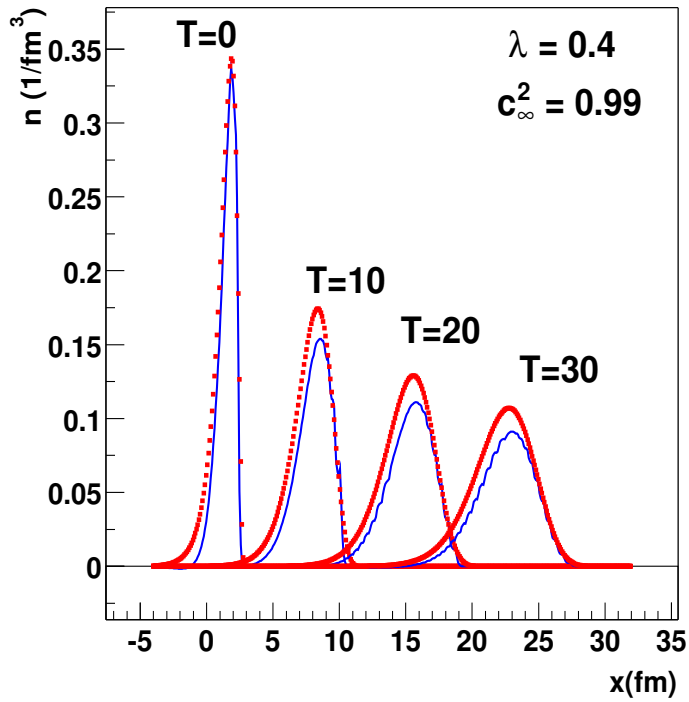
$$s_{\pm} = \frac{v \pm c_{\infty}}{1 \pm vc_{\infty}}$$
$$c_{\infty}^2 \equiv \frac{\lambda}{\tau}$$

- Disturbances propagate with speed c_{∞} in the local reference frame.
- c_{∞} is of order the typical thermal velocity.
- If choose τ arbitrarily then the signals propagate faster than the speed of light.

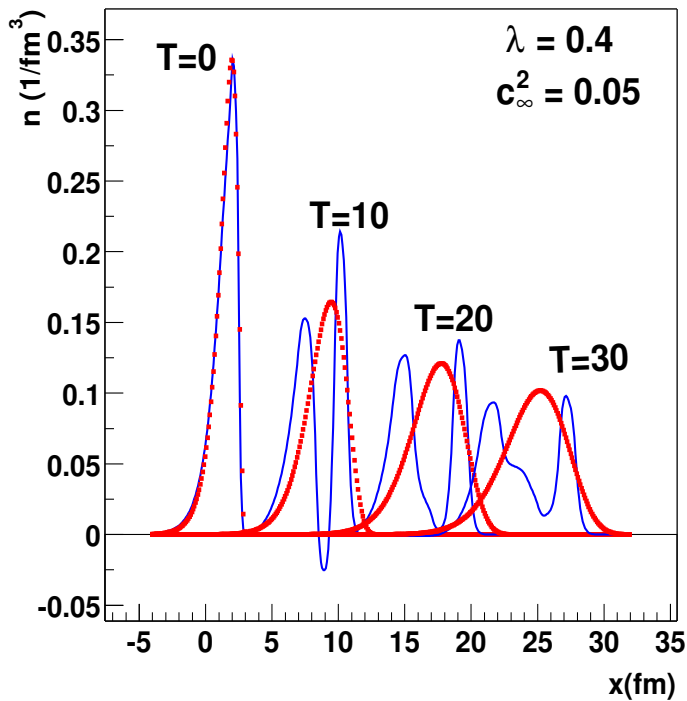
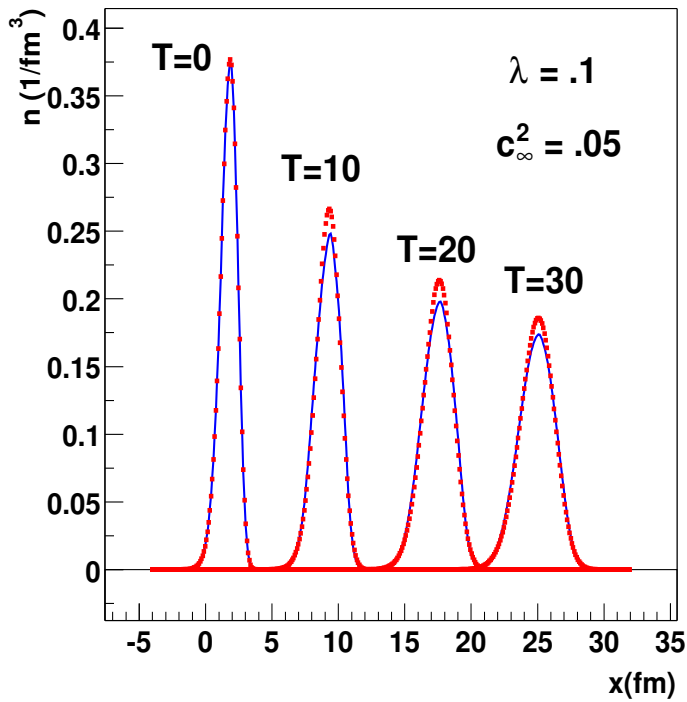
Small Diffusion Coefficient: $v=0.85$!



Large Diffusion Coefficient: $v=0.85$!

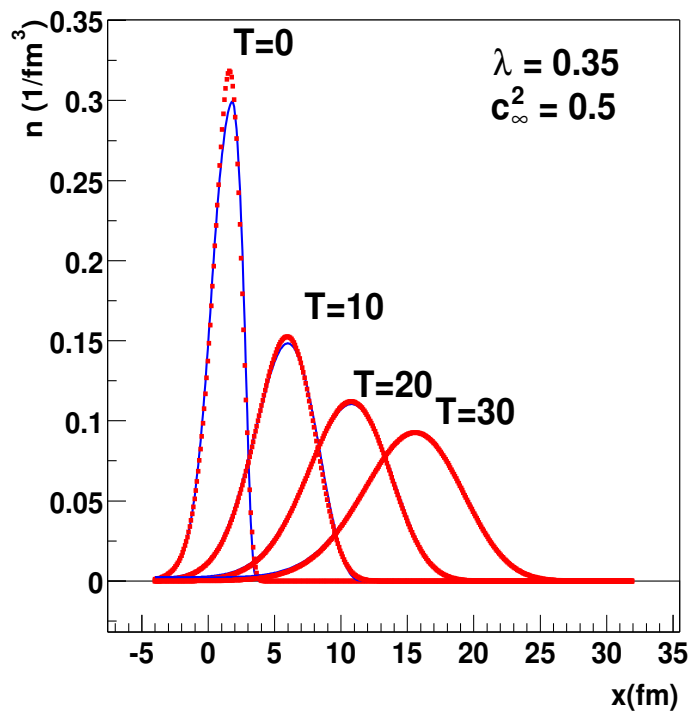


Problems when signal velocity $\rightarrow 0$



Goes crazy when outside regime of validity.

For more typical parameters $v=.5$, λ large



Conclusions

- Choose λ/τ to make the theory causal
- Compute λ/τ from short time response of correlation function
- For final results it does not matter what you choose/calculate for λ/τ .

Only λ matters

- Always get ordinary Navier Stokes in the end.

Generalize this discussion to the Navier-Stokes Case:

Most naive approach:

$$T^{\mu\nu} = e u^\mu u^\nu + p \Delta^{\mu\nu} + \tau^{\mu\nu}$$

Where $\tau^{\mu\nu}$ vanishes in the rest frame : $\tau^{\mu\nu} u_\mu = 0$

and relaxes to equilibrium to over a time scale τ_c .

$$\Delta^{\mu\alpha} \Delta^{\nu\beta} D\tau_{\alpha\beta} = -\frac{\tau^{\mu\nu} + \eta \langle \nabla^\mu u^\nu \rangle}{\tau_c}$$

This is a pretty messy partial differential equation.

Let us look at the mode structure in one dimension.

The Riemann-Characteristic Problem

Write the equations of motion in the following form:

$$\begin{pmatrix} \mathbf{B} \end{pmatrix} \begin{pmatrix} \partial_t e \\ \partial_t u^x \\ \partial_t \tau^{xx} \end{pmatrix} + \begin{pmatrix} \mathbf{A} \end{pmatrix} \begin{pmatrix} \partial_x e \\ \partial_x u^x \\ \partial_x \tau^{xx} \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ -\tau^{xx} / \tau_c \end{pmatrix}$$

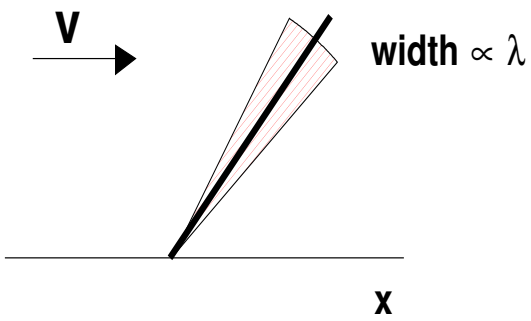
The **eigen values/vectors** of $\mathbf{B}^{-1}\mathbf{A}$ are the **signal velocities** of the equation of motion.

$$\begin{aligned} s_0 &= v \\ s_{\pm} &= \frac{v \pm c_{\infty}}{1 \pm v c_{\infty}} \\ c_{\infty}^2 &\equiv c_s^2 + \frac{\frac{4}{3}\eta/(e+p)}{\tau_c} \end{aligned}$$

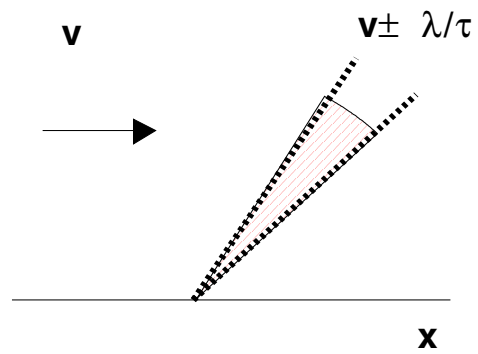
- Disturbances propagate with speed c_{∞} in the local reference frame.
- c_{∞} is of order the typical thermal velocity.
- If choose τ arbitrarily then the signals propagate faster than the speed of light.

Summary Of Mode Structure:

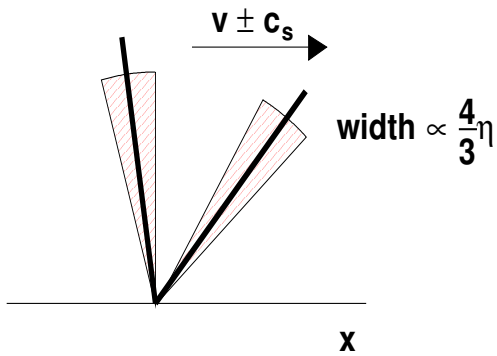
Advection Diffusion



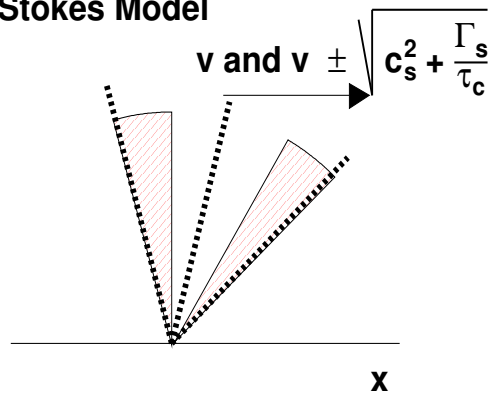
Advection Diffusion Model



Navier Stokes



Navier Stokes Model



Remarkable observation: (L. Lindblom and R. Geroch)

The Navier Stokes Equation in the Eckart Frame can be written as a set of conservation/balance laws:

$$\begin{aligned}\partial_\mu(N^\mu) &= 0 \\ \partial_\mu(T^{\mu\nu}) &= 0 \\ \partial_\mu(A^{\mu\alpha\beta}) &= I^{\alpha\beta}\end{aligned}$$

where

$$\begin{aligned}N^\mu &= nu^\mu \\ T^{\mu\nu} &= \epsilon u^\mu u^\nu + p\Delta^{\mu\nu} + u^\mu q^\nu + u^\nu q^\mu + \tau^{\mu\nu} \\ A^{\mu\alpha\beta} &= 2T\Delta^{\mu(\alpha}u^{\beta)} \\ I^{\alpha\beta} &= -\frac{T}{\eta}\tau^{\alpha\beta} - \frac{2T}{3\sigma}\Delta^{\alpha\beta} - \frac{2T}{\kappa T}(q^\alpha u^\beta + q^\beta u^\alpha)\end{aligned}$$

Verify that (simple and key) :

$$\partial_\mu A^{\mu\alpha\beta} = T \langle \nabla^\alpha u^\beta \rangle + \text{Tensors of different symmetry}$$

Compare the terms in $\partial_\mu(A^{\mu\alpha\beta}) = I^{\alpha\beta}$ with the same symmetry:

$$T \langle \nabla^\alpha u^\beta \rangle = -\frac{T}{\eta}\tau^{\alpha\beta}$$

Now add a new contribution to $A^{\mu\alpha\beta}$:

$$B^{\mu\alpha\beta} = C_0 u^\mu \tau^{\alpha\beta}$$

Note that:

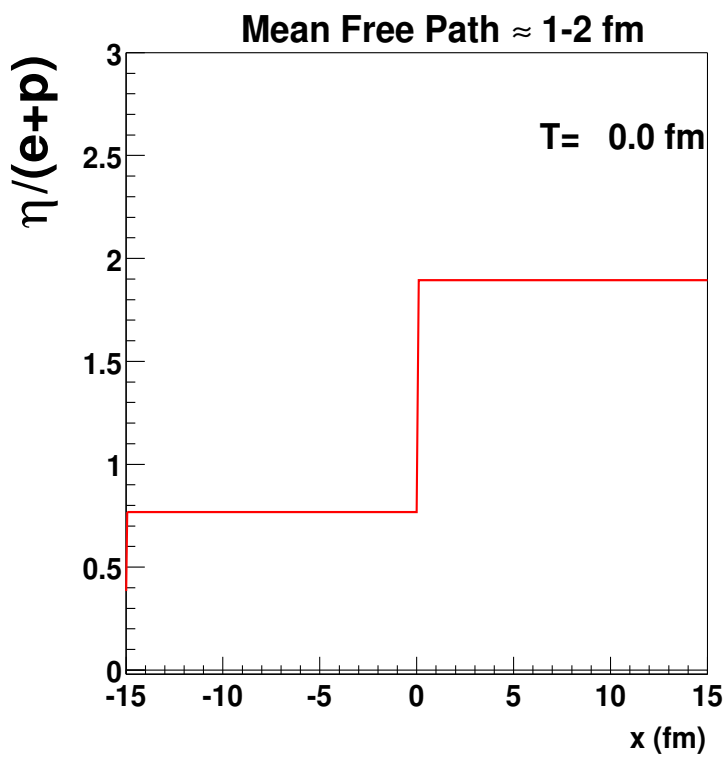
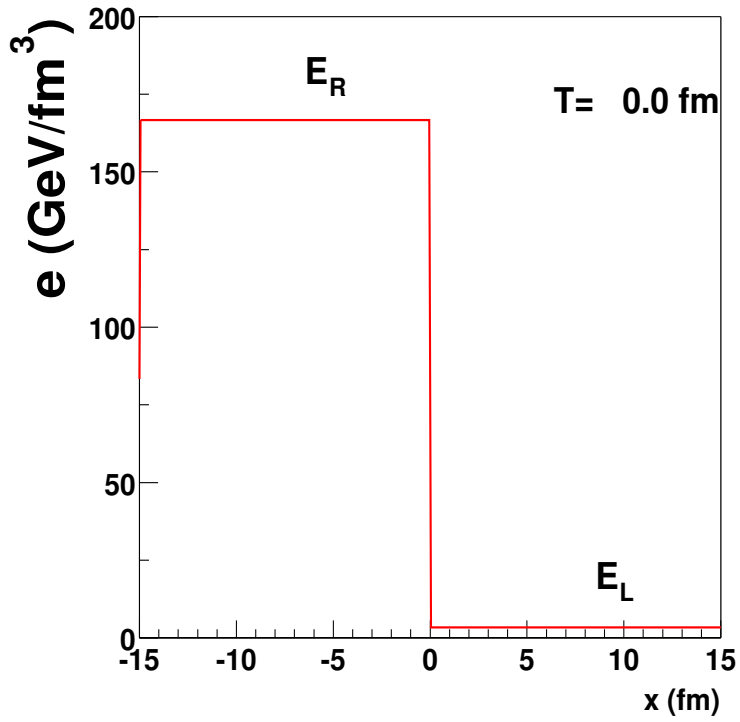
$$\partial_\mu B^{\mu\alpha\beta} \approx C_0 u^\mu \partial_\mu \tau^{\alpha\beta} \approx C_0 D\tau^{\alpha\beta}$$

Then we see:

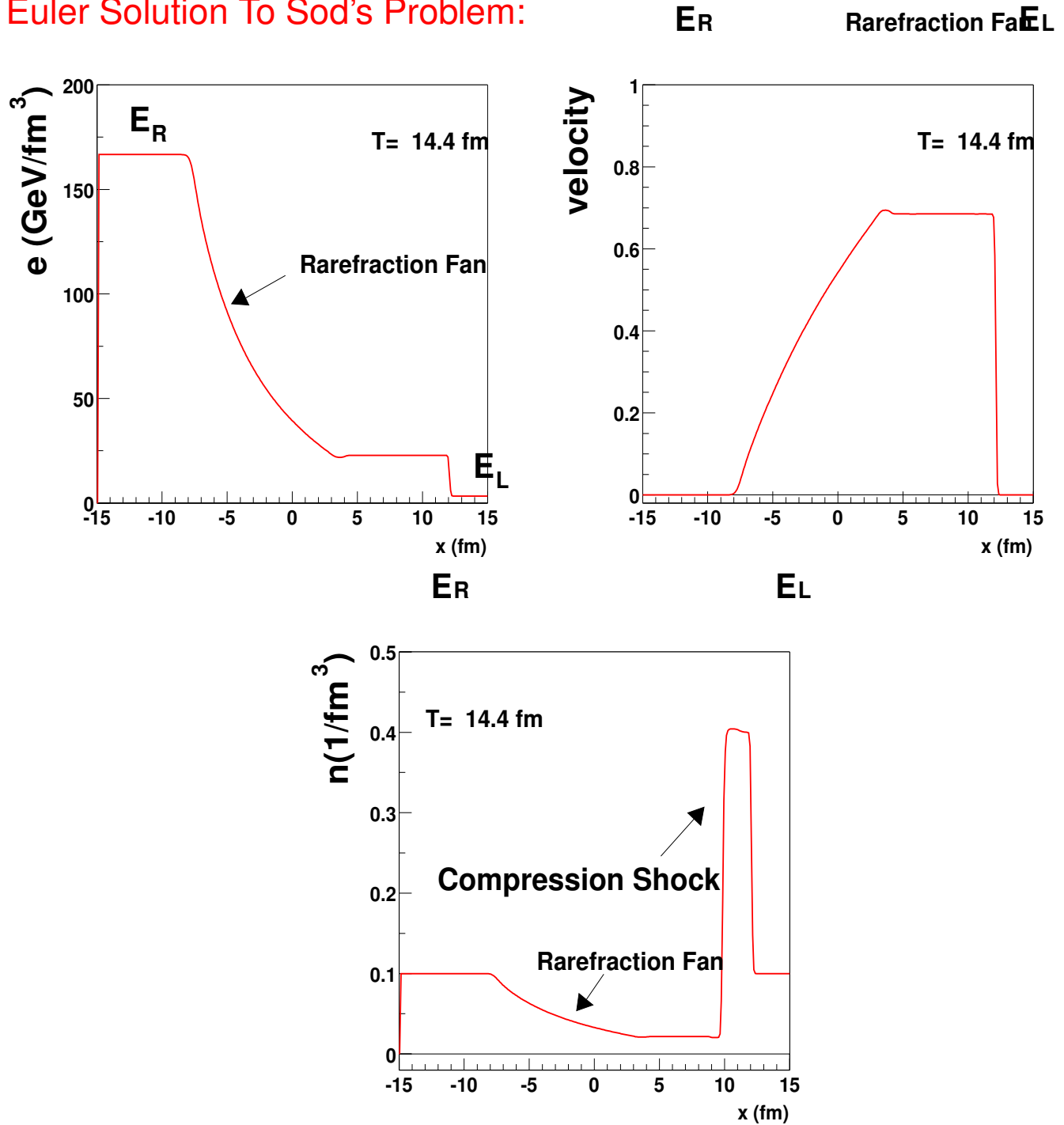
$$\begin{aligned} \partial_\mu (B^{\mu\alpha\beta} + A^{\mu\alpha\beta}) &= -\frac{T}{\eta} \tau^{\alpha\beta} + \text{Other symmetry} \\ C_0 D\tau^{\alpha\beta} + \langle \nabla^\alpha u^\beta \rangle &= -\frac{T}{\eta} \tau^{\alpha\beta} + \text{Other symmetry} \end{aligned}$$

- This is the relaxation equation with a stiff source term.
- The relaxation equation can be formulated as a conservation law. (L. Linblom and R. Geroch)
- Can relate C_0 to τ_c and c_∞^2 . It doesn't matter what you take for c_∞^2
- The relaxation models are not unique. Can add many such terms.

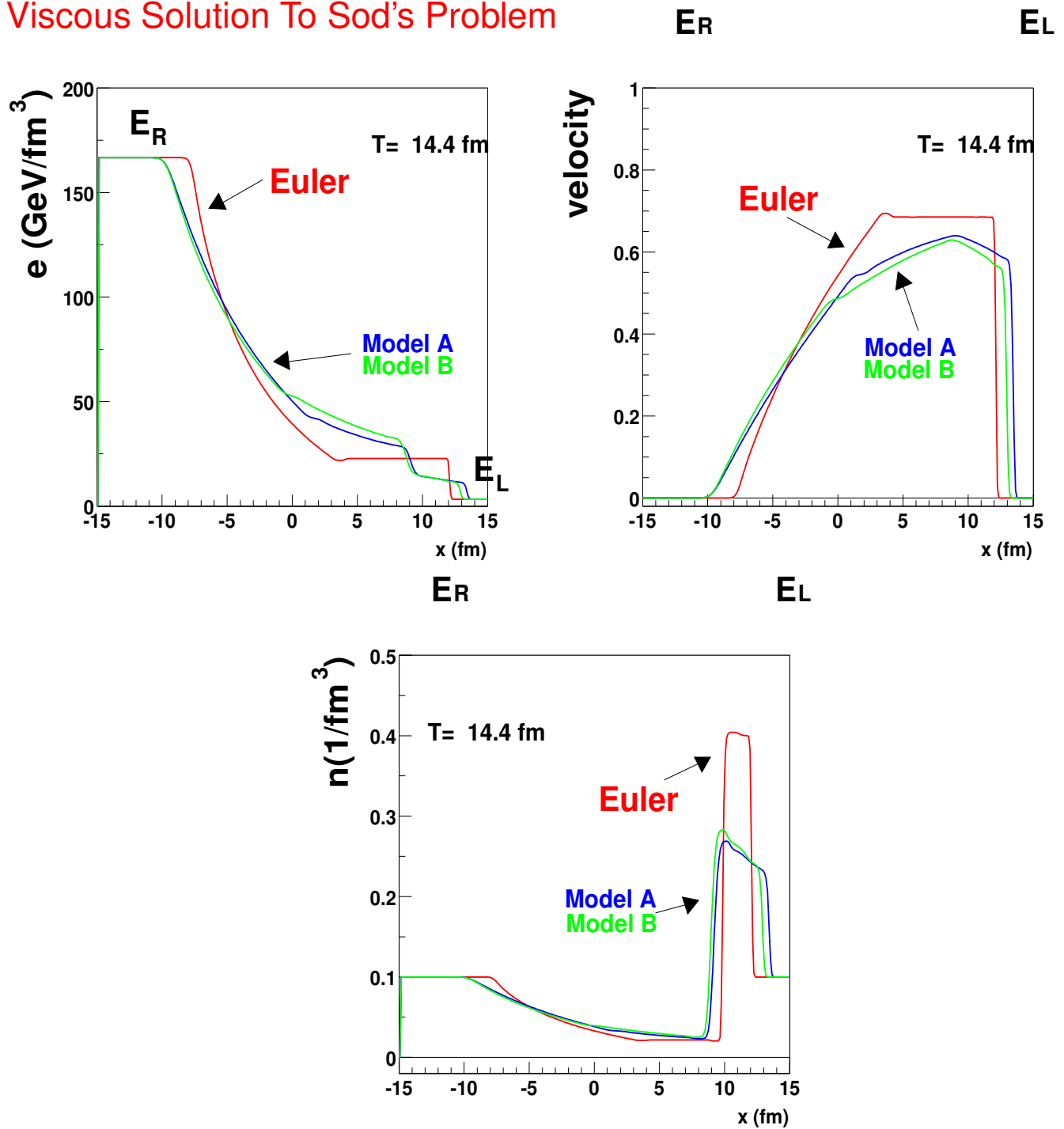
A Test Problem: Sod's Problem



Euler Solution To Sod's Problem:



Viscous Solution To Sod's Problem



All Models are the SAME:

The static Correlator:

$$\lim_{k \rightarrow 0} \int e^{ikr} \langle n(r, \sigma) n(0, \sigma) \rangle = \langle n(0) n(0) \rangle_{k=0} + O\left(\frac{k^2}{T^2}\right)$$

Can be related to a thermodynamic deriv.

$$\delta N_k = \int_V d^3x e^{ik \cdot x} n(x)$$

$$\begin{aligned} \langle \delta N_k \delta N_{k'} \rangle &= \int_V d^3x d^3x' e^{ikx} e^{ik'x'} \langle n(x) n(x') \rangle \\ &= V \delta_{k+k'} \int e^{ik\Delta x} \langle n(\Delta x) n(0) \rangle \\ &= V \delta_{k+k'} \langle n(0) n(0) \rangle_k \end{aligned}$$

Set $k=0$

$$\frac{1}{V} \langle (\delta N_0)^2 \rangle = \langle n(0) n(0) \rangle_{k=0}$$

$$\delta N_0 = N - \langle N \rangle$$

$$\langle N \rangle = \frac{\text{Tr} [N e^{-\beta H + \mu N}]}{\text{Tr} [e^{-\beta H + \mu N}]}$$

$$\frac{\partial \langle N \rangle}{\partial \mu} = \langle \delta N_0^2 \rangle$$

Dividing by Volume:

$$\frac{\partial n}{\partial \mu} = \langle n(0) n(0) \rangle_{k=0} = \int d^3 \Delta x \langle n(\Delta x) n(0) \rangle$$

Long Time Tails

$$\partial_t \langle n(t) n(0) \rangle_k = -\lambda k^2 \langle n(t) n(0) \rangle_k$$

Or

$$\langle n(t) n(0) \rangle_k = e^{-\lambda k^2 t} \langle n(0) n(0) \rangle_{k=0} + \mathcal{O}\left(\frac{k^2}{T^2}\right)$$

Go Back to coordinate space

$$\langle n(x, t) n(x', 0) \rangle = e^{-\frac{(\Delta x)^2}{2\lambda t}} \left(\frac{\partial n}{\partial \mu}\right) (\lambda t)^{3/2}$$

Expand $t \gg \frac{L^2}{\lambda}$

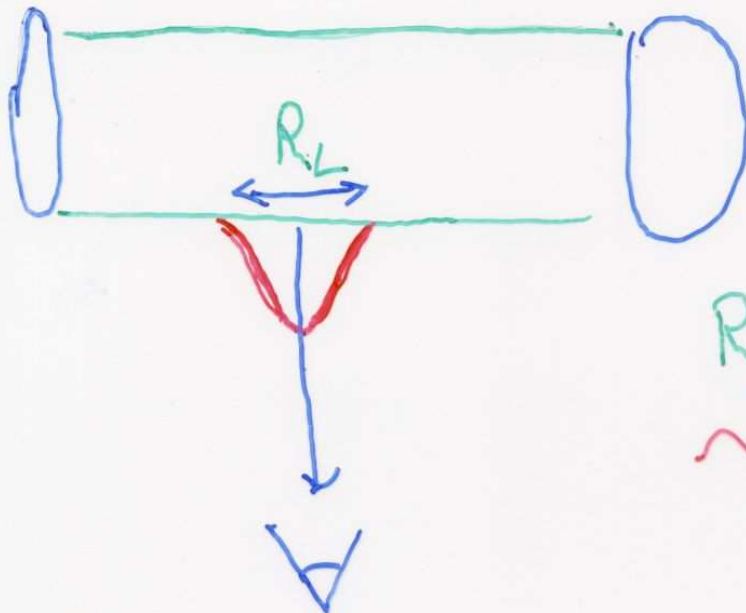
$$e^{-\frac{\Delta x^2}{2\lambda t}} = 1 + \mathcal{O}\left(\frac{L^2}{\lambda t}\right)$$

Integrate: over $\int \frac{d^3x}{V}$ and $\int \frac{d^3x'}{V}$

$$\left\langle \frac{N(t)}{V} \frac{N(0)}{V} \right\rangle = \left(\frac{\partial n}{\partial \mu}\right) \frac{1}{(\lambda t)^{3/2}} \propto \frac{1}{t^{3/2}}$$

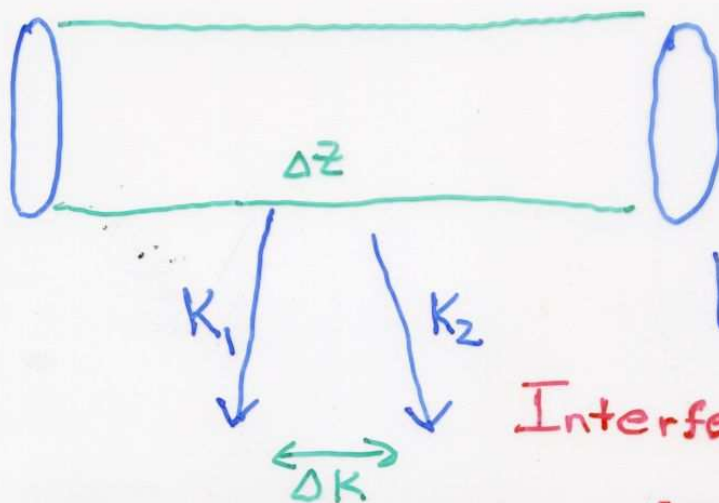
- For $t \gg \frac{L^2}{\lambda}$ the correlator falls off as $\frac{C}{t^{3/2}}$
- From C can determine λ

HBT Radii



$$R_L^2 = \langle z^2 \rangle_{k_T}$$

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$$|e^{ik_1 z_1} + e^{ik_2 z_2}|^2$$

Interfere:

$$\Delta k \Delta z \sim 1$$

## Summary:

- Viscosity Effects Many Observables
- The size of the Correction depends upon the observable

Example

$\langle P_T^{100} \rangle \rightarrow$  Big Correct.

$\langle P_T \rangle \rightarrow$  Small Correct.